# CONVERGENCE RATE OF EMPIRICAL ESTIMATES IN STOCHASTIC PROGRAMMING 

## Vlasta KAŇKOVÅ and Petr JACHOUT

Institute of Information Theory and Automation
Czechoslovak Academy of Sciences
18208 Prague, Pod vodárenskou vèżí 4, Czechoslovakia


#### Abstract

It is well known that many practical optimization problems with random elements lead from the mathematical point of view to deterministic optimization problems depending on the randöm elements through probibility laws only. Further, it is also well known that these probability laws are known very seldom. Consequently, statistical estimates of the unknown probability measure, if they exist, must be employed to obtain some estimates of the optimal value and the optimal solution, at least.

If the theoretical distribution function is completely unknown then an empirical distribution usually substitutes it $[2,3,9,17,31]$. The great attention has been already paid to the studying of statistical properties of such arised empirical estimates, in the literature. We can remember here the works [4, 5, 6 , $10,13,16,32]$, for example. The aim of this paper is to discuss the convergence rate. For this we shall employed the assertions of the papers [10, 11, 13].

Key words: stochastic programming, problem with penalty, deterministic equivalent, random sequence fulfilling $\Phi$-mixing condition.


1. Introduction. Let ( $\Omega, \mathcal{S}, P$ ) be probability space, $\xi=\xi(\omega)=$ $\left[\xi_{1}\left(\omega, \ldots, \xi_{s}(\omega)\right]\right.$ be an $s$-dimensional random vector defined on $(\Omega, \mathcal{S}, P), F(z)$ be the distribution function of the random vector $\xi(\omega), Z \subset E_{s}$ denote the support of the probability measure corresponding to the distribution fation $F(z), g_{i}(x, z), i=0,1,2, \ldots, \ell$ be real valued continuous functions defined on $E_{n} \times E_{s}, X \subset E_{n}$ be a nonempty set ( $E_{n}, n \geqslant 1$ denotes an $n$-dimensional Euclidean space).

The general optimization problem with random element can be introduced as the problem to find

$$
\begin{equation*}
\min \left\{g_{0}(x, \xi(\omega)) \mid x \in X: g_{i}(x, \xi(\omega)) \leqslant 0, i=1,2, \ldots, \ell\right\} \tag{1}
\end{equation*}
$$

It happens rather often that the solution $x$ must be found without the realization knowledge of the random vector $\xi(\omega)$. Evidently, it is necessary, first to determine the decision rule, in such situation. It means to set to the original stochastic optimization problem (1) some deterministic equivalent. Two well known types of the deterministic equivalents can be introduced as the following deterministic problems.
I. To find

$$
\inf \{E \tilde{g}(x, \xi(\omega)) \mid x \in X\}
$$

Stochastic programming problems with penalty and two-stage stochastic programming probiems belong to this class of optimization problems.
II. To find
$\inf \left\{E g(x, \xi(\omega)) \mid \dot{x} \in X: P\left\{\omega: g_{i}(x, \xi(\omega)) \leqslant 0, i=1,2, \ldots, \ell\right\} \geqslant \alpha\right\}$.
This deterministic equivalent is known as the chance constrained stochastic programming problem, from the literature.
$\alpha \in\langle 0,1\rangle$ is a parameter, $\bar{g}(x, z), g(x, z)$ some real valued continuous functions defined on $E_{n} \times E_{s}, E$ denotes the operator of the mathematical expectation.
Remarks:

1. The choice of the functions $\bar{g}(.,),. g(.,$.$) depends on the char-$ acter of the original stochastic problem.
2. It can generally happen that some above mentioned symbols are not meaningful. However, this situation cannot appear under the assumptions considered in this paper.
3. It is easy to see that I is a special case of II, from the mathematical point of view. We consider these problems separately, according to the historical development and their specific properties.

If we define the sets $Z(x), X(\alpha), \alpha \in E_{1}, x \in E_{n}$ by the prescription

$$
\begin{align*}
& X(\alpha)=\left\{\begin{array}{lr}
\{x \in X: P[Z(x)] \geqslant \alpha\} & \text { for } \alpha \in\langle 0,1\rangle, \\
X(1) & \text { for } \alpha>1, \\
X(0) & \text { for } \alpha<0,
\end{array}\right.  \tag{2}\\
& Z(x)=\left\{z \in E_{S}: g_{i}(x, z) \leqslant 0, i=1,2, \ldots, \ell\right\},
\end{align*}
$$

then we can rewrite the deterministic equivalent II in the form: to find

$$
\begin{equation*}
\inf _{X(\alpha)} E g(x, \xi(\omega)) . \tag{3}
\end{equation*}
$$

If, further, $\xi^{k}(\omega)=\xi^{k}=\left[\xi_{1}^{k}(\omega), \ldots, \xi_{b}^{k}(\omega)\right]$ is a sequence of random vectors with the common distribution function $F(z)$, the functions $U_{i}(z, \omega)=U_{i}(z), F_{N}(z, \omega)=F_{N}(z), z=\left(z_{1}, \ldots, z_{s}\right) \in E_{s}$, $\omega \in \Omega, k=1,2, \ldots, N, N=1,2, \ldots$ are defined by

$$
\begin{aligned}
& U_{k}(z, \omega)=1 \Longleftrightarrow \xi_{j}^{k}(\omega)<z_{j} \text { for all } j=1,2, \ldots, s, \\
&=0 \Longleftrightarrow \xi_{j}^{k}(\omega) \geqslant z_{j} \text { for at least one } j \in\{1,2, \ldots, s\}, \\
& F_{N}(z, \omega)=\left(\frac{1}{N}\right) \sum_{k=1}^{N} U_{k}(z, \omega) .
\end{aligned}
$$

$E_{N}$ and $P_{N}, N=1,2, \ldots$ denote the operator of mathematical expectation and probability measure corresponding to the distribution function $F_{N}(\cdot)$, the set mapping $X_{N}(\alpha)=X_{N}(\alpha, \dot{\omega}), N=$ $1,2, \ldots, \alpha \in\langle 0,1\rangle, \omega \in \Omega$ is defined by the prescription

$$
X_{N}(\alpha)=X_{N}(\alpha, \omega)=\left\{x \in X: P_{N}[Z(x)] \geqslant \alpha\right\},
$$

then under general conditions $\inf _{x \in X} E_{N} \bar{g}(x, \xi(\omega))$ estimates the value $\inf _{x \in X} E \bar{g}(x, \xi(\omega))$ in the case of the deterministic equivalent I. In the case of the deterministic equivalent II the theoretical value $\inf _{X(\alpha)} E g(x, \xi(\omega))$ can be estimated by the value $\inf _{X_{N}(\alpha)} E_{N} g(x$, $\xi(\omega)$ ).

The statistical behaviour of tae just introduced estimates has been studied in the literature many times. We can remember here the works $[2,3,6,9,12,32]$, where the conditions are given under
which these estimates are consistent. Fuither, the rate convergence was studied in $[10,11,22,29,30]$. In detail, mostly the upper bound for the expressions

$$
\begin{aligned}
& P\left\{\omega:\left|\inf _{X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{X} E \bar{g}(x, \xi(\omega))\right|>t\right\}, \\
& P\left\{\omega:\left|\inf _{X_{N(\alpha)}} E_{N} g(x, \xi(\omega))-\inf _{X(\alpha)} E g(x, \xi(\omega))\right|>t\right\},
\end{aligned}
$$

$t>0$, were presented there.
Further, the asymptotic distributions of the random value $\sqrt{N}\left(\bar{x}_{N}(\omega)-\bar{x}\right)$ was studied in $[4,5,16,17,32]$,

$$
\begin{gather*}
\bar{x}=\arg \min _{X} E \bar{g}(x, \xi(\omega)),  \tag{4}\\
\bar{x}_{N}(\omega)=\bar{x}_{N}=\arg \min _{X} E_{N} \bar{g}(x, \xi(\omega)) .
\end{gather*}
$$

In this paper we shall try to present some tighter results for the convergence rate. In detail, we shall determine $\beta>0$ such that

$$
\begin{align*}
& P\left\{\omega: N^{\beta}\left|\inf _{X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{X} E \bar{g}(x, \xi(\omega))\right|>t\right\} \rightarrow(N \rightarrow \infty) 0, \\
& P\left\{\omega: N^{\beta} \mid \inf _{X_{N}{ }^{\prime} \alpha} E_{N} g(x, \xi(\omega))\right. \\
& \left.\quad-\inf _{\{(\alpha)} E g(x, \xi(\omega)) \mid>t\right\} \rightarrow(N-\infty) 0 \tag{6}
\end{align*}
$$

for every $t>0$.
Further, if $\bar{g}(:, z), g(\cdot, z)$ are uniformly strongly convex with parameter $\rho>0$ functions of $x \in X$ (for the definition of strongly convex functions see Definition 3), then we have also $\beta>0$ such that

$$
\begin{equation*}
P\left\{\omega: N^{\beta}\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2}>t\right\} \rightarrow(N \rightarrow \infty) 0 \tag{7}
\end{equation*}
$$

and

$$
\begin{equation*}
P\left\{\omega: N^{\beta}\left\|x_{N}(\alpha, \omega)-x(\alpha)\right\|^{2}>t\right\} \rightarrow(N-\infty) 0, \tag{8}
\end{equation*}
$$

$\bar{x}_{N}(\omega), \bar{x}$ fulfil the relation (4) and $x_{N}(\alpha, \omega)=x_{N}(\alpha), x(\alpha)$ are defined by

$$
\begin{align*}
x_{N}(\alpha, \omega) & =x_{N}(\alpha)=\arg \min _{X_{N}(\alpha)} E_{N} g(x, \xi(\omega)),  \tag{9}\\
x(\alpha) & =\arg \min _{X(\alpha)} E g(x, \xi(\omega))
\end{align*}
$$

We shall employ the works $[10,11,13]$ to obtain the above mentioned results. Consequently, some types of stochastic dependent random samples will be included into our investigation. However, we restrict our consideration to the case when

$$
g_{i}(x, z)=f_{i}(x)-z_{i}, \quad i=1,2, \ldots, \ell
$$

in the case of the deterministic equivalent II. $f_{i}(x), i=1,2, \ldots, \ell$ are some real valued continuous functions defined on $E_{n}$.

Evidently, it holds $\ell=s$ in the case. "
2. Some auxiliary definitions. In this part we shall remember some definitions. The Hausdorff distance between two subsets in $E_{n}$ is defined by the following way:

Definition 1. If $X^{\prime}, X^{\prime \prime} \subset E_{n}, n \geqslant 1$ are two non-empty sets then the Hausdorff distance of these sets is defined by

$$
\begin{aligned}
\Delta_{n}\left[X^{\prime}, X^{\prime \eta}\right] & =\max \left[\delta_{n}\left(X^{\prime}, X^{\prime \prime}\right), \delta_{n}\left(X^{\prime \prime}, X^{\prime}\right)\right] \\
\delta_{n}\left[X^{\prime}, X^{\prime \prime}\right] & =\sup _{x^{\prime} \in X^{\prime}} \inf _{x^{\prime \prime} \in X^{\prime \prime}}\left\|x^{\prime}-x^{\prime \prime}\right\| .
\end{aligned}
$$

$\|\cdot\|$ denotes the Euclidean norm in $E_{n}$.
(We usually omit the subscripts in the symbols $\Delta_{n}, \delta_{n}$.)
Let $\left\{\eta^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ be an $s$-dimensional strongly stationary random sequence defined on $(\Omega, \mathcal{S}, P), \mathcal{B}(-\infty, a)$ be the $\sigma$-algebra given by $\ldots, \eta^{a-1}(\omega), \eta^{a}(\omega), \mathcal{B}(b,+\infty)$ be the $\sigma$-algebra given by $\eta^{b}(\omega)$, $\eta^{b+1}(\omega), \ldots:(a, b$ are integers $)$.

If $\mathcal{N}$ denotes the set of all natural numbers, $\phi(\cdot)$ is a nonnegative real valued function defined on $\mathcal{N}$ then we can define the $\phi$-mixing random sequence by the following definition from [1].

Definition 2. We say that the strongly stationary random sequence $\left\{\eta^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ fulfils the condition of $\phi$-mixing if

$$
\left|P\left(A_{1} \cap A_{2}\right)-P\left(A_{1}\right) P\left(A_{2}\right)\right| \leqslant \phi(N) P\left(A_{1}\right)
$$

for $A_{1} \in \mathcal{B}(-\infty, m), A_{2} \in \mathcal{B}(m+N,+\infty),-\infty<m<+\infty, N \geqslant 1, m$ is an integral number.

Further, we shall remember one definition of convex analysis:
Definition 3. Let $\bar{h}(x)$ be a real valued function defined on a convex set $\mathcal{K} \subset E_{n} . \bar{h}(x)$ is a strongly convex function with the parameter $\rho>0$ if

$$
\bar{h}\left(\lambda x_{1}+(1-\lambda) x_{2}\right) \leqslant \lambda \bar{h}\left(x_{1}\right)+(1-\lambda) \bar{h}\left(x_{2}\right)-\lambda(t-\lambda) \rho\left\|x_{1}-x_{2}\right\|^{2} .
$$

for every $x_{1}, x_{2} \in \mathcal{K}, \lambda \in\langle 0,1\rangle$.
Remark. The assumptions under which a function is a strongly convex one with a parameter $\rho>0$ are introduced in [20]; for example.

It is known that the class of logarithmic concave probability measures is very important for change constrained stochastic programming problems $[8,18,19]$. If $\mathcal{B}_{s}$ denotes the Borel $\sigma$-algebra of the subsets of $E_{s}$ then we can already remember the corresponding definition [18].

Definition 4. A probability measure $P(\cdot)$ defined on the $\mathcal{B}_{s}$ is logarithmic concave if for every $A, B \in \mathcal{B}_{s}$ and for every $\lambda \in\langle 0,1\rangle$ the following ineqfality,

$$
\left.P_{i}^{[ } \lambda A+(1-\lambda) B\right] \geqslant[P(A)]^{\lambda}[P(B)]^{1-\lambda}
$$

holds. $(\lambda A+(1-\lambda) B$ means Minkowski addition of sets.)
If $D \subset E_{n}$ is a bounded set then there exist $d_{j}^{\prime}, d_{j}^{\prime \prime} \in E_{1}, j=$ $1,2, \ldots, n$ and natural numbers $m_{j}=m_{j}(D, d), j=1,2, \ldots, n$ for $d>0, d \in E_{1}, d<\min _{j}\left(d_{j}^{\prime \prime}-d_{j}^{\prime}\right)$ such that

$$
\begin{align*}
d_{j}^{\prime}(D) & =d_{j}^{\prime}=\inf \left\{x_{j}: x=\left(x_{1,}, \ldots, x_{n}\right) \in D\right\},  \tag{10}\\
d_{j}^{\prime \prime}(D)=d_{j}^{\prime \prime} & =\sup \left\{x_{j}: x=\left(x_{1}, \ldots, x_{n}\right) \in D\right\}, \\
D_{j} \frac{\sqrt{n}}{d} & \leqslant m_{j}<D_{j} \frac{\sqrt{n}}{d}+1, \quad D_{j}=d_{j}^{\prime \prime}-d_{j}^{\prime} .
\end{align*}
$$

Further, we can define $x_{j_{1}}, \ldots, x_{j m_{j}}, j \neq 1,2, \ldots, n$ such that

$$
\begin{aligned}
& d_{j}^{\prime}=x_{j_{1}}, x_{j_{r}}=x_{j_{r-1}}+\left(\frac{d}{\sqrt{n}}\right), r=2, \ldots, m_{j}, \\
& x_{j m_{j}-1}<d_{j}^{\prime \prime}, x_{j m_{j}} \geqslant d_{j}^{\prime \prime}, j=1,2, \ldots, n,
\end{aligned}
$$

and the system $S$ as the following

$$
S=S(D, d)=\left\{x=\left[x_{1}, \ldots, x_{n}\right]: x_{i} \in\left[x_{i j_{1}}, \ldots, x_{i m_{i}}\right], i=1,2, \ldots, n\right\} .
$$

It holds that

$$
\begin{array}{lll}
\inf _{x^{\prime} \in S}\left\|x-x^{\prime}\right\| \leqslant d & \text { for all } & x \in D, \\
\inf _{x^{\prime} \in S}\left\|x-x^{\prime}\right\| \leqslant d & \text { for all } & x \in \prod_{j=1}^{n}\left\langle d_{j}^{\prime}, d_{j}^{\prime \prime}\right\rangle
\end{array}
$$

and

$$
\begin{equation*}
m=\prod_{j=1}^{n} m_{j} \tag{11}
\end{equation*}
$$

where we denote by $m=m[D, d]$ the number of the elements of the system $S$.

At the end of this part we denote the surroundings of a nonempty set $X \subset E_{n}$ by the symbol $X[\delta]$. It means that

$$
X[\delta]=\left\{x \in E_{n}: x=x_{1}+x_{2}, x_{1} \in X, x_{2} \in \mathcal{B}(\delta)\right\},
$$

where $\mathcal{B}(\delta)$ is the $\delta$-surroundings of zero in $E_{n}$.
3. Main results. The aim of this section is to present the values $\beta>0$ for which the relations (5), (6), (7), (8) hold. More precisely, we shall try to obtain the results for the case when either $\left\{\xi^{k}(\omega)\right\}_{k=1}^{\infty}$ is a sequence of independent random vectors or when $\left\{\xi^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ fulfils the $\phi$-mixing condition.

Our investigation will be devided into two parts. We shall deal separately with the deterministic equivalent $I$ and the deterministic equivalent II. The reason for this is practical especially in the mathematical technic of proof. Moreover, the interval for $\beta$ will be rather greater in the deterministic equivalent I. In detail, this interval does not depend on the dimension of the random vector $\xi(\omega)$. Further, the results achieved for this simpler case will be employed to obtain the results for the deterministic equivalent II. However, we start our investigation by very simple case of deterministic equivalent I. By this access it will be seen the dependence of interval for $\beta$ on the complexity of the corresponding problems.
a) Deterministic equivalent I. We shall consider a special, simple case, at the beginning. So first, let us assume that there exist a natural number $s_{1}$ and continuous functions $g_{i}^{*}(z), h_{i}^{*}(x)$, $i=1,2, \ldots, s_{1}$, defined on $E_{s} \times E_{n}$ such that

$$
\begin{equation*}
\bar{g}(x, z)=\sum_{i=1}^{s_{1}} g_{i}^{*}(z) h_{i}^{*}(x) . \tag{12}
\end{equation*}
$$

We shall see that in this very special case (however from the mathematical point of view enough important) the terminal result will be the same in the both considered cases.

Theorem 1. Let $X$ be a compact set, the function $\bar{g}(x, z)$ fulfils the relation (12), where $g_{i}^{*}(z)$ and $h_{i}^{*}(x), i=1,2, \ldots, s_{1}$, are continuous, real valued, bounded functions defined on $Z \times X$. If either

1. $\left\{\xi^{k}(\omega)\right\}_{k=1}^{\infty}$ is a sequeace of independent random vectors or
2. $\left\{\xi^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ is a strongly stationary random sequence fulfilling the $\phi$-mixing condition for which there exists

$$
\overline{\lim }_{N \rightarrow \infty} \frac{1}{N} \sum_{k=1}^{N-1}(N-k) \phi(k)<+\infty,
$$

then

$$
\begin{aligned}
& P\left\{\omega: N^{\beta}\left|\inf _{x \in X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{x \in X} E \bar{g}(x, \xi(\omega))\right|>t\right\} \rightarrow_{(N \rightarrow \infty)} 0 \\
& \quad \text { for } t>0, \beta \in\left(0, \frac{1}{2}\right) .
\end{aligned}
$$

If moreover
3. $X$ is a convex set,
4. $h_{i}^{*}(x) i=1,2, \ldots, s_{1}$, are convex functions on $X$,
5. there exists $i \in\left\{1,2, \ldots, s_{1}\right\}$ such that $h_{i}^{*}(x)$ is a strongly convex with a parameter $\rho>0$ function on $X$,
then also

$$
P\left\{\omega: N^{\beta}\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2}>t\right\} \rightarrow_{(N-\infty)} 0
$$

for $t>0, \beta \in(0,1 / 2)$.
(Remark: $\bar{x}_{N}(\omega), \bar{x}, N=1,2, \ldots$ are defined by the relation (4).)
Proof. The assertion of Theorem 1 follows immediately from the next Theorem. It is sufficient to employe there the substitution $t:=\left(t /\left(N^{\beta}\right)\right)$ and generally known limit properties of the corresponding functions.

Theorem 2. Let $X$ be a a compact set and the function $\bar{g}(x, z)$ fulfil the relation (12) where $g_{i}^{*}(z)$ and $h_{:}^{*}(x), i=1,2, \ldots, s_{1}$, are continuous real valued functions defined on $Z \times X$. Let further $K_{1}$, $M_{1}$ be real valued constants such that

$$
\because\left|g_{i}^{*}(z)\right| \leqslant K_{1}, \quad\left|h_{i}^{*}(x)\right| \leqslant M_{1}, \quad x \in X, \quad z \in Z, i=1,2, \ldots, s_{1}
$$

If

1. $\left\{\xi^{k}(\omega)\right\}_{k=1}^{\infty}$ is a sequence of independent random vectors, - then

$$
\begin{align*}
& P\left\{\omega:\left|\inf _{x \in X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{x \in X} E \bar{g}(x, \xi(\omega))\right|>t\right\} \\
& \quad \leqslant 2 s_{1} \cdot \exp \left\{-\frac{N t^{2}}{2 M_{1}^{2} K_{1}^{2} s_{1}^{2}}\right\} \text { for } N=1,2, \ldots, t>0 \tag{13}
\end{align*}
$$

2. $\left\{\xi^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ is a strongly stationary random sequence fulfilling the $\phi$-mixing condition then

$$
\begin{align*}
& P\left\{\omega:\left|\inf _{x \in X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{x \in X} E \bar{g}(x, \xi(\omega))\right|>t\right\} \\
& \quad \leqslant s_{1}^{3} \frac{4 K_{1}^{2} M_{1}^{2}}{t^{2} N^{2}}\left[N+\sum_{k=1}^{N-1}(N-k) \phi(k)\right] \tag{14}
\end{align*}
$$

$$
N=1,2, \ldots, t>0 .
$$

## If moreover

3. $X$ is a convex set,
4. $h_{i}^{*}(x) i=1,2, \ldots, s_{1}$, are contex functions on $X$,
5. there exists $i \in\left\{1,2, \ldots, s_{1}\right\}$ such that $h_{i}^{*}(x)$ is a strongly convex with a parameter $\rho>0$ function, then also
in the case 1

$$
\begin{aligned}
& P\left\{\omega:\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2}>\frac{2 t}{\rho}\right\} \leqslant 4 s_{1} \exp \left\{-\frac{N t^{2}}{2 M_{1}^{2} K_{1}^{2} s_{1}^{2}}\right\} \\
& \quad \text { for } N=1,2, \ldots, t>0
\end{aligned}
$$

and in the case 2

$$
\begin{align*}
& P\left\{\omega:\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2}>\frac{2 t}{\rho}\right\} \leqslant 2 s_{1}^{3} \frac{4 K_{1}^{2} M_{1}^{2}}{t^{2} N^{2}}\left[N+\sum_{k=1}^{N-1}(N-k) \phi(k)\right] \\
& \quad \text { for } N=1,2, \ldots, t>0 \tag{16}
\end{align*}
$$

The proof of Theorem 2 will be given in the Appendix.
It follows from the assertion of Theorem 1 that the interval for $\beta$ is the same in the both considered cases. According to well known results of $[4,5,16,32]$ we can recognize that it is not possible this interval to expand. However, Theorem 1 deals only with the very special form of the function $\bar{g}(x, z)$. Further, we shall consider rather general case.

## Theorem 3. Let

1. $X \subset E_{n}$ be á compact set,
2. $\bar{g}(x, z)$ be continuous, bounded function on $X[d] \times Z$ for . some $d>0$,
3. $\bar{g}(x, z)$ be for every $z \in Z$ a Lipschitz function of $x \in X[d]$ with the Lipschitz constant $L$ not depending on $z \in Z$.
If
4. either
a) $\left\{\xi^{k}(\omega)\right\}_{k=1}^{\infty}$ is a sequence of independent random vectors and simultaneously $0<\beta<1 / 2$,
or
b) $\left\{\xi^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ is a strongly stationary random sequence fulfilling the $\phi$-mixing condition for which

$$
\overline{\lim }_{N \rightarrow \infty} \frac{1}{N} \sum_{k=1}^{N-1}(N-k) \phi(k)<+\infty
$$

and simultaneously $0<\beta<1 /(n+2)$, then
$P\left\{\omega: N^{\beta}\left|\inf _{x \in X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{x \in X} E \bar{g}(x, \xi(\omega))\right|>t\right\} \rightarrow(N-\infty) 0$,
for $t>0$.
If moreover
5. $X$ is a convex set,
6. $\tilde{g}(x, z)$ is for every $z \in Z$ a strongly convex with a parameter $p>0$ function of $x \in X[d]$,
then also

$$
P\left\{\omega: N^{s}\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2}>t\right\} \rightarrow(N \rightarrow \infty) 0,
$$

for $t>0$.
To prove the assertion of Theorem 3 we shall employ some former results [10, 11]. However, we introduce them in a modified form.

Theorem 4. If the assumptions $1,2,3$ of Theorem 3 are fulfilled and if $\left\{\xi^{k}(\omega)\right\}_{k=1}^{\infty}$ is a sequence of independent random vectors then

$$
\begin{align*}
& P\left\{\omega:\left|E_{N} \bar{g}(x, \xi(\omega))-E \bar{g}(x, \xi(\omega))\right|>t L \text { for at least one } x \in X[d]\right\} \\
& \quad \leqslant 2 m\left[X,\left(\frac{t}{3}\right)\right] \exp \left\{-\frac{N t^{2}}{18 M^{2}}\right\}, \\
& \text { and simultaneously }  \tag{17}\\
& \quad \therefore \quad P\left\{\omega:\left|\inf _{X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{x \in X} E \bar{g}(x, \xi(\omega))\right|>t L\right\} \\
& \quad \leqslant 2 m\left[X,\left(\frac{t}{3}\right)\right] \exp \left\{-\frac{N t^{2}}{18 M^{2}}\right\},
\end{align*}
$$

for $0<t<3 d$ and a constant $M$ fulfilling the inequality $|\bar{g}(x, z)| \leqslant M$, $x \in X[d], z \in Z$.

If moreover the assumptions 5, 6 of Theorem 3 are satisfied, then also

$$
\begin{equation*}
P\left\{\omega:\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2} \geqslant t L \cdot\left(\frac{2}{\rho}\right)\right\} \leqslant 4 m\left[X,\left(\frac{t}{3}\right)\right] \exp \left\{-\frac{N t^{2}}{18 M^{2}}\right\} . \tag{18}
\end{equation*}
$$

Theorem 5. If the assumptions 1, 2, 3 of Theorem 3 are fulfilled and if $\left\{\xi^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ is a strongly stationary random sequence fulfilling the $\phi$-mixing conditions, then

$$
\begin{aligned}
P & \left\{\omega:\left|\inf _{x \in X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{x \in X} E \bar{g}(x, \xi(\omega))\right|>t L\right\} \\
& \leqslant m\left[X,\left(\frac{t}{3}\right)\right] \frac{36 M^{2}}{t^{2} N^{2}}\left[N+\sum_{k=1}^{N-1}(N-k) \phi(k)\right]
\end{aligned}
$$

and simultaneously

$$
\begin{align*}
& P\left\{\omega:\left|E_{N} \bar{g}(x, \xi(\omega))-E \bar{g}(x, \xi(\omega))\right|>t L \text { for at least one } x \in X[d]\right\}  \tag{19}\\
& \quad \leqslant m\left[X,\left(\frac{t}{3}\right)\right]\left[N+\sum_{k=1}^{N-1}(N-k) \phi(k)\right] \cdot \frac{36 M^{2}}{t^{2} N^{2}},
\end{align*}
$$

for $0<t<3 d$ and a constant $M$ fulfilling the inequality $|\bar{g}(x, z)| \leqslant M$, $x \in X[d], z \in Z$ :

If moreover the assumptions 5, 6 of Theorem 3 are statisfied, then also

$$
\begin{align*}
& P\left\{\omega:\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2} \geqslant \frac{2 L t}{\rho}\right\} \\
& \quad \leqslant 2 r\left[X,\left(\frac{t}{3}\right)\right] \frac{36 M^{2}}{t^{2} N^{2}}\left[N+\sum_{k=1}^{N-1}(N-k) \phi(k)\right] . \tag{20}
\end{align*}
$$

The assertions given by the relations (17) and (19) follow immediately from the results of the papers $[10,11]$. (Theorem 2 and its proof in [10] and also Theorem 2 and the corresponding proof in [11]). It remains to prove the relation (18), (20). However this results will be proved in the Appendix. Here we shall prove the assertion of Theorem 3 only.

Proof of Theorem 3. To prove the assertion of Theorem 3 we shall first find an upper estimate of the number $m[X, d]$. For this we shall verify the validity of the auxiliary assertion.

Lemma 1. If $X \subset E_{n}$ is a nonempty, bounded set, $d>0$, then

$$
m[X, d] \leqslant\left[\frac{\operatorname{rad} X \cdot \sqrt{n}}{d}+1\right]^{n}
$$

.where $\operatorname{rad} X=\sup _{\boldsymbol{x}, z^{\prime} \in X}\left\|x-x^{\prime}\right\|$.
Proof. Since it follows from definition of the number $m[X, d]$ that

$$
m[X, d] \leqslant \prod_{j=1}^{n}\left[\frac{D_{j} \sqrt{n}}{d}+1\right]
$$

we can see that the assertion of Lemma 1 holds.
Consequently, as $X$ is a compact set, it follows from Lemma 1 that

$$
m\left[X,\left(\frac{t}{3}\right)\right] \leqslant \sum_{k=0}^{n}\binom{n}{k}\left[\frac{\mathrm{rad} X}{t} \cdot 3 \sqrt{n}\right]^{k},
$$

for $t>0$.
Further, if we substitute (in Theorems 4,5$) t:=t /\left(L N^{\beta}\right)$ then there exists a natural number $N_{0}$ and a constant $K=K(n, X)$ such that

$$
L N^{\beta} \frac{\operatorname{rad} X}{t} \sqrt{n}>1 \quad \text { for } \quad N>N_{0},
$$

and simultaneously

$$
\begin{equation*}
m\left[X, \frac{t}{3 L N^{\beta}}\right] \leqslant K(n, X) \frac{N^{n \beta}}{t^{n}} . \tag{21}
\end{equation*}
$$

Now already the validity of the assertion of Theorem 3 follows from the last inequality, Theorems 4 and 5 and well known limit properties of the corresponding functions.

We have finished the part of the section 3 corresponding to the deterministic equivalent I. Comparing these results with the ones of the works $[4,6]$ (where the problems of asymptotic distribution of $\sqrt{N}\left(\bar{x}_{N}(\omega)-\bar{x}\right)$ is discussed), we can believe that it is impossible to expand the interval for $\beta$ at least in the case of independent random samples.

Further, it follows from Theorem 1 that the same interval can be achieved in special cases for dependent samples too. Of course, it was done only for the case when the optimalized function satisfy the relation (12) and the random samp.e satisfy the $\phi$-mixing condition.

The chance constrained stochastic programming problems will be considered in the next part of this section. We shall see that the
interval for $\beta$ will be smaller everywhere, it means in the case of independent random samples too. This is evidently draw by new ineccuraccy arising by the set $X(\alpha)$ approximation.
b) Deterministic equivalent II. We have already mentioned that employing the results of the works $[12,13]$ we have to restrict the original stochastic problem in the case of the deterministic equivalent II. In detail, we have to deal with the original stochastic problems in which the random element appears on the constraints right-hand side only. So we shall assume that there exist real valued functions $f_{i}(x), i=1,2, \ldots, \ell$ defined on $E_{n}$ such that

$$
g_{i}(x, z)=f_{i}(x)-z_{i}, \quad i=1,2, \ldots, \ell .
$$

Consequently $\ell=s$. Of course, the original optimalized function may depend on the random element as well. Now, we shall repeat the definition of some symbols in this case.

Let $f_{i}(x), i=1,2, \ldots, \ell$ be real valued, continuous functions defined on $E_{n}, n \geqslant 1$,

$$
\begin{array}{rlrl}
X & =E_{n}^{+}, \\
Z & \subset E_{\ell}^{+}, & \\
Z(x) & =\left\{z \in E_{\ell}^{+}: z=\left(z_{1}, \ldots, z_{\ell}\right), f_{i}(x) \leqslant z_{i}, i=1,2, \ldots, \ell\right\}, \\
X(\alpha) & =\left\{x \in E_{n .}^{+}: P[Z(x)] \geqslant \alpha\right\} & & \text { for } \alpha \in\langle 0,1\rangle, \\
& \equiv X(1) & & \text { for } \alpha>1, \\
& \equiv X(0) & & \text { for } \alpha<0, \\
X_{N}(\alpha) & =\left\{x \in E_{n}^{+}: P_{N}[Z(x)] \geqslant \alpha\right\} & & \text { for } \alpha \in\langle 0,1\rangle,
\end{array}
$$

where $P[Z(x)]=P\{\omega: \xi(\omega) \in Z(x)\} ; P_{N}[]=P_{N}\{\cdot, \omega\}$ is the empirical probability measure corresponding to the distribution function $F_{N}(\cdot), E_{n}^{+}=\left\{x \in E_{n}: x=\left(x_{1}, \ldots, x_{n}\right), x_{i} \geqslant 0, i=1,2, \ldots, n\right\}$.

Let further

$$
\begin{align*}
x(\beta) & =\arg \min _{X(\beta)} E g(x, \xi(\omega)),  \tag{23}\\
x_{N}(\beta, \omega) & =\arg \min _{X_{N}(\beta)} E_{N} g(x, \xi(\omega)) \quad \text { for } \beta \in(0,1) .
\end{align*}
$$

If $\delta>0, \alpha \in(0,1)$ are arbitrary chosen but fix in the sequel we set the following assumptions.
i) $f_{i}(x), i=1,2, \ldots, \ell$ are real valued continuous functions on $E_{n}^{+}$ such that
a) $f_{i}(0)=0, i=1,2, \ldots, \ell, 0 \in E_{n}$,
b) there exist a constant $\gamma_{1}$ such that

$$
f_{i}(x)-f_{i}\left(x^{\prime}\right) \geqslant \gamma_{1} \sum_{j=1}^{n}\left(x_{j}-x_{j}^{\prime}\right)
$$

for every $x=\left(x_{1}, \ldots, x_{n}\right), x^{\prime}=\left(x_{1}^{\prime}, \ldots, x_{n}^{\prime}\right), x \geqslant x^{\prime}$ componentwise, $i=1,2, \ldots, \ell, x, x^{\prime} \in E_{n}^{+}$,
c) there exists a constant $\gamma_{2}>0$ such that

$$
\left|f_{i}(x)-f_{i}\left(x^{\prime}\right)\right| \leqslant \gamma_{2}| | x-x^{\prime}| |
$$

for $i=1,2, \ldots, \ell, x, x^{\prime} \in X(\alpha, 2 \delta), x<x^{\prime}$ componentwise, $X(\alpha, \delta)$ is defined by the following relation

$$
X(\alpha, \delta)=\left\{x=x_{1}+x_{2}: x_{1} \in X(\alpha), x_{2} \in \mathcal{B}(\delta)\right\}
$$

where $B(\delta)$ denotes the $\delta$-surrounding of $0 \in E_{n}$.
ii) $\boldsymbol{\xi}(\omega)$ fulfils the conditions:
a) the probability measure of the random vector $\xi(\omega)$ is absolutely continuous with respect to the Lebesgue measure in $E_{\ell}$. Let us denote by $h(z)$ the probability density corresponding to the distribution function $F(z)$ of the random vector $\xi(\omega)$;
b) there exist real numbers $c_{j}, j=1,2, \ldots, \ell$ such that $c_{j}>0$ and $Z=\prod_{j=1}^{\ell}\left\langle 0 ; c_{j}\right\rangle$ (it means $P\left\{\omega: \xi(\omega) \in \prod_{j=1}^{\ell}\left\langle 0, c_{j}\right\rangle\right\}=1$ );
c) there exist $\vartheta_{1}, \vartheta_{2}$ such that

$$
0<v_{1} \leqslant h(z) \leqslant v_{2} \quad \text { for every } z \in \prod_{j=1}^{\ell}\left\langle 0, c_{j}\right\rangle
$$

iii)
a) $g(x, z)$ is a bounded function on $E_{n} \times Z$,
b) $g(x, z)$ is for every $z \in Z$ a Lipschitz function of $x \in X(\alpha, \delta)$ with Lipschitz constant $L$ not depending on $z \in Z$,
iv) at least one of the following assumptions is satisfied:
a) $\left\{\xi^{k}(\omega)\right\}_{k=1}^{\infty}$ is a sequence of independent random vectors and simultaneously $0<\beta<1 /(2 \ell)$,
b) $\left\{\xi^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ is a strongly stationary random sequence fulfilling the $\phi$-mixing condition for which

$$
\overline{\lim }_{N \rightarrow \infty} \frac{1}{N} \sum_{k=1}^{N-1}(N-k) \phi(k)<+\infty
$$

and simultaneously $0<\beta<1 /((n+2) \ell)$.
v) $g(x, z)$ is for every $z \in Z_{\text {/ }}$ strongly convex with parameter $\rho>0$ function on $X(\alpha, \delta)$,
vi) $f_{i}(x), i=1,2, \ldots, \ell$ are convex function on $E_{n}^{+}$,
vii) the probability measure corresponding to $F(z)$ is logarithmic concave.
Now we can already introduce the main result of this part of the paper.

Theorem 6. Let $X=E_{n}^{+}$and the assumptions i , ii, iii, iv be fulfilled for given arbitrary $\alpha \in(0,1), \delta>0$. If $t>0$ then
$P\left\{\omega: N^{\beta}\left|\inf _{x \in X(\alpha)} E f(x, \xi(\omega))-\inf _{x \in X_{N}(\alpha)} E_{N} g(x, \xi(\omega))\right|>t\right\} \rightarrow(N \rightarrow \infty) 0$. If moreover the assumptions v , vi, vii are fulfilled, then also

$$
P\left\{\omega: N^{\beta}\left\|x_{N}(\alpha, \omega)-x(\alpha)\right\|^{2}>t\right\} \rightarrow(N \rightarrow \infty) 0 .
$$

To prove the assertion of Theorem 6 we shall employ the former results [13]. However we shall have to employ them in modified forms, again.

Theorem 7. Let $\left.\alpha \in(0,1), \delta>0, t>0, t_{0}=4\left(\sqrt{n} / \gamma_{1}\right)\right)$ $\sqrt[f]{2 t /\left(\vartheta_{1}\right)}$. Let, further, the assumptions i, ii, iii be fulfilled. If $d<\min (\delta, t / 6),\left(\sqrt{n} /\left(\gamma_{1}\right)\right) \sqrt[f]{2 t /\left(v_{1}\right)}<\delta, \vartheta_{2} \gamma_{2} d \sum_{i=1}^{l} \Pi_{\nu \neq i} c_{v}<t / 6, M$ is a constant for which $|g(x, z)| \leqslant M, x \in X(\alpha, 2 \delta), z \in Z$ and if $\left\{\xi^{k}(\omega)\right\}_{k=1}^{\infty}$ is a sequence of independent random vectors, then

$$
\begin{align*}
P\{\omega & \left.:\left|\inf _{x \in X(\alpha)} E g(x, \xi(\omega))-\inf _{x \in X_{N}(\alpha)} E_{N} g(x, \xi(\omega))\right|>t_{0} L\right\} \\
& \leqslant 2 m[X(\alpha, 2 \delta), d] \exp \left\{-N t^{2} / 18\right\}  \tag{24}\\
& +2 m[X(\alpha, 2 \delta), d] \exp \left\{-N t_{0}^{2} L^{2} / 4 \cdot 18 M^{2}\right\} .
\end{align*}
$$

- If moreover the assumptions v , vi, vii are fulfilled, then also

$$
\begin{align*}
P\{\omega: & \left.\left\|x_{N}(\alpha, \omega)-x(\alpha)\right\|^{2} \geqslant 4 \frac{t_{0} L}{\rho}\right\} \\
& \leqslant 6 m[X(\alpha, 2 \delta), d] \exp \left\{-N t^{2} / 18\right\}  \tag{25}\\
& +4 m[X(\alpha, 2 \delta), d] \exp \left\{-N t_{0}^{2} L^{2} / 4 \cdot 18 M^{2}\right\} .
\end{align*}
$$

Theorem 8. Let $\alpha \in(0,1), \delta>0, t>0, t_{0}=4\left(\sqrt{n} /\left(\gamma_{1}\right)\right)$ $\sqrt[2]{2 t /\left(\vartheta_{1}\right)}$. Let, further, the assumptions i, ii, iii be fulfilled. If $d<\min (\delta, t / 6),\left(\sqrt{n} /\left(\gamma_{1}\right)\right) \sqrt[6]{2 t /\left(\vartheta_{1}\right)}<\delta, \vartheta_{2} \gamma_{i}^{2} d \sum_{i=1}^{\ell} \prod_{v \neq i} c_{v}<t / 6, M$ is a constant for which $|g(x, z)| \leqslant M, x \in X(\alpha, 2 \delta), z \in Z$ and if $\left\{\xi^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ is a random sequence fulfiling a $\phi$-mixing condition, then

$$
\begin{align*}
& P\left\{\omega:\left|\inf _{X(\alpha)} E g(x, \xi(\omega))-\inf _{X_{N}(\alpha)} E_{N} g(x, \xi(\omega))\right|>t_{0} L\right\} \\
& \quad \leqslant m[X(\alpha, 2 \delta), d]\left[N+\sum_{k=1}^{N-1}(N-k) \phi(k)\right]\left[\frac{36 \cdot 4}{t^{2} N^{2}}+\frac{4 \cdot 36 M^{2}}{L^{2} t_{0}^{2} N^{2}}\right] . \tag{26}
\end{align*}
$$

If moreover the assumptions v , vi, vii are fulfilled, then also

$$
\begin{align*}
P\{\omega & \left.:\left\|x_{N}(\alpha, \omega)-x(\alpha)\right\|^{2} \geqslant 4 \frac{t_{0} L}{\rho}\right\} \\
\leqslant & 3 m[X(\alpha, 2 \delta), d]\left[N+\sum_{k=1}^{N-1}(N-k) \phi(k)\right] \cdot \frac{36 \cdot 4}{t^{2} N^{2}}  \tag{27}\\
& +2 m[X(\alpha, 2 \delta), d]\left[N+\sum_{k=1}^{N-1}(N-k) \phi(k)\right] \cdot \frac{4 \cdot 36 M^{2}}{L^{2} t_{0}^{2} N^{2}} .
\end{align*}
$$

The assertions given by the relations (24) and (26) follows immediately from the results of the paper [13]. It remains to prove the relation (25), (27). The proof of this resuits will be given in the Appendix. Here we shall prove the assertion of Theorem 6, only.

Proof of Theorem 6, To prove the assertion of Theorem 6 we shall have first to determine an upper estimate of the number $m[X(\alpha, 2 \delta), d]$ for $d=t /\left(7 N^{\beta}\right)$. However, employing the results of Lemma 1 and further following the cr rresponding part of Theorem 3 proof we obtain that

$$
m[X(\alpha, 2 \delta), d] \leqslant \tilde{k}(n ; X(\alpha)) \frac{N^{n \beta}}{t^{n}}
$$

for enough large $N$ and some constant $\bar{k}(n, X(\alpha))$.
Now already, the validity of the assertion of Theorem 6 follows from the last inequality, Theorems 7 and 8 , the substitution $t_{0}=t /\left(L N^{\beta}\right)$ and well known limit properties of the corresponding functions.
4. Appendix. The aim of this section is to give a proof of the introduced but unverified results. First, we prove some auxiliary assertions.

Lemma 2. Let $K \subset E_{n}$ be a non-empty, compact convex set. Let, further, $\bar{h}(x)$ be a strongly convex with a parameter $\rho>3$, continuous, real valued function defined on $K$. If $x_{0} \in K$ is determined by the relation

$$
x_{0}=\arg \min _{x \in K} \bar{h}(x)
$$

then

$$
\left\|x-\dot{x}_{0}\right\|^{2} \leqslant\left(\frac{2}{\rho}\right)\left[\bar{h}(x)-\bar{h}\left(x_{0}\right)\right],
$$

for every $x \in K$.
Proof. We refer to the paper [14], for this proof. There namely, the proof of the corresponding assertion for concave functions is. presented. Besides this, the assertion of Lemma 2 has already been introduced in [28], too.

If we denote by the symbol $B_{s}$ the Borel $\sigma$-algebra in $E_{s}$ then we can remember one well known inequality from the probability theory.

## Lemma 3. If

1. $\kappa(z)$ is a measurable (according to $B_{s}$ ) function defined on $E_{s}$ such that there exists a constant $\bar{M}$ fulfilling the inequality $|\kappa(z)| \leqslant \bar{M}$ for all $z \in E_{s}$,
2. $\left\{\xi^{k}(\omega)\right\}_{k=1}^{\infty}$ is a sequence of independent random vectors, then

$$
P\left\{\omega: E_{N} \kappa(\xi(\omega))-E \kappa(\xi(\omega))>t\right\} \leqslant \exp \left\{-\frac{N t^{2}}{2 \bar{M}^{2}}\right\},
$$

for, every $t \in E_{1}, t>0$.
Proof. The inequality introduced in Lemma 3 has been first proved in [7].

Further, we present one result for $\phi$-mixing random sequences.
Lemma 4. If the assumption 1 of Lemma 3 is fulfilled and if $\left\{\xi^{k}(\omega)\right\}_{k=-\infty}^{\infty}$ is a strongly stationary random sequence fulfilling the $\phi$-mixing condition, then

$$
\begin{aligned}
P\{\omega & \left.:\left|E_{N} \kappa(\xi(\omega))-E \kappa(\xi(\omega))\right|>t\right\} \\
& \leqslant \frac{2 \bar{M}^{2}}{t^{2} N^{2}}\left[N+\sum_{k=1}^{N-1}(N-k) \phi(k)\right] .
\end{aligned}
$$

Proof. First, it follows from Lemma 2, Chapter 4 of [1]

$$
\begin{equation*}
\left|E\left[\kappa\left(\xi^{k}(\omega)\right)-E \kappa(\xi(\omega))\right]\left[\kappa\left(\xi^{\tau}(\omega)\right)-E \kappa(\xi(\omega))\right]\right| \leqslant 2 \bar{M}^{2} \phi(|r-k|) \tag{28}
\end{equation*}
$$

for $r \neq k, r, k=\ldots-2,-1,0,1,2, \ldots$.
Since it follows from Chebyshev's inequality that

$$
\begin{aligned}
P\{\omega & \left.:\left|E_{N} \kappa(\xi(\omega))-E \kappa(\xi(\omega))\right|>t\right\} \\
& \left.\leqslant \frac{1}{t^{2} N^{2}} E \right\rvert\, \sum_{k=1}^{N}\left[\left.\kappa\left(\xi^{i}(\omega)-E \kappa(\xi(\omega))\right]\right|^{2}\right.
\end{aligned}
$$

and since

$$
E\left[\kappa\left(\xi^{i}(\omega)-E \kappa(\xi(\omega))\right]=0 \quad \text { for every } i=\ldots,-2,-1,0,1,2, \ldots,\right.
$$

we obtain the assertion of Lemma 4 immediately from the relation (28).

Now, we can already present the proof of Theorem 2.
Proof of Theorem 2. Let $t>0$ be arbitrary given. Since it follows from the relation (12) that

$$
\left|E_{N} \bar{g}(x, \xi(\omega))-E \bar{g}(x, \xi(\omega))\right| \leqslant \sum_{i=1}^{\varepsilon_{1}} M_{1}\left|E_{N} g_{i}^{*}(\xi(\omega))-E g_{i}^{*}(\xi(\omega))\right|,
$$

we can obtain successfully further

$$
\begin{align*}
P\{\omega & \left.:\left|\inf _{x \in X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{x \in X} E \bar{g}(x, \xi(\omega))\right|>t\right\} \\
& \leqslant P\left\{\omega:\left|E_{N} \bar{g}(x, \xi(\omega))-E \bar{g}(x, \xi(\omega))\right|>t \text { for at least one } x \in X\right\} \\
& \leqslant \sum_{i=1}^{s_{1}} P\left\{\omega:\left|E_{N} g_{i}^{*}(\xi(\omega))-E g_{i}^{*}(\xi(\omega))\right|>\frac{t}{M_{1} s_{1}}\right\} . \tag{29}
\end{align*}
$$

Employing now Lemma 3 and Lemma 4 we obtain immediately the validity of the assertion (13) and (14).

It remains to prove the validity of the relations (15), (16). However, evidently if the assumptions $3,4,5$ of Theorem 2 are satisfied then $E \bar{g}(x, \xi(\omega))$ is a strongly convex with the parameter $\rho$ function. So, according to Lemma 2 it is

$$
\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2} \leqslant\left(\frac{2}{\rho}\right)\left|E \bar{g}\left(\bar{x}_{N}(\omega), \xi(\omega)\right)-E \bar{g}(\bar{x}, \xi(\omega))\right|,
$$

for all $\omega \in \Omega, N=1,2, \ldots$ and $E \bar{g}\left(\bar{x}_{N}(\omega), \xi(\omega)\right)=[E \bar{g}(x, \xi(\omega))]_{x=x_{N}(\omega)}$.
Employing the triangular inequality we get

$$
\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2} K\left(\frac{2}{\rho}\right)\left\{\left|E \bar{g}\left(\bar{x}_{N}(\omega), \xi(\omega)\right)-E_{N} \bar{g}\left(\bar{x}_{N}(\omega), \xi(\omega)\right)\right|\right.
$$

for all $\omega \in \Omega, N=1,2, \ldots$ and so also -

$$
\begin{aligned}
& P\left\{\omega:\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2}>t \cdot\left(\frac{2}{\rho}\right)\right\} \\
& \leqslant P\left\{\omega:\left|E \bar{g}(x, \xi(\omega))-E_{N} \bar{g}(x, \xi(\omega))\right|>\left(\frac{t}{2}\right) \text { for at least one } x \in X\right\} \\
&+P\left\{\omega:\left|\inf _{x \in X} E_{N} \bar{g}(x, \xi(\omega))-\inf _{x \in X} E \bar{g}(x, \xi(\omega))\right|>\left(\frac{t}{2}\right)\right\} .
\end{aligned}
$$

Now already we obtain the validity of the relations (15), (16) on the basis of the inequalities given by the relations (13), (14), (29), Lemma 3 and Lemma 4. By this we have finished the proof of Theorem 2.

Theorems 4 and 5 generalize the results of Theorem 2 to rather great class of the optimalized functions. Of course, the achieved upper bound is higher. Namely, there appears the factor $m(X,(t / 3))$
in the relations (17), (18), (19), (20). We shall present here the proof of the new part of the assertion of Theorem 4.

Proof of Theorem 4. The assertion given by the relations (17) follows immediately from the results of the paper [10] (Theorem 2 and its proof). So it remains to prove the assertion given by the relation (18). Since $E \bar{g}(x, \xi(\omega))$ is a strongly convex with the parameter $\rho>0$ function on $X[d]$ we can apply the idea of the second part proof of Theorem 2 to get successfully

$$
\begin{aligned}
\left\|\bar{x}_{N}(\omega)-\bar{x}\right\|^{2} \leqslant & \left(\frac{2}{\rho}\right)\left|E \bar{g}\left(\bar{x}_{N}(\omega), \xi(\omega)\right)-E \bar{g}(\bar{x}, \xi(\omega))\right| \\
\leqslant & \left(\frac{2}{\rho}\right)\left\{\left|E \bar{g}\left(\bar{x}_{N}(\omega), \xi(\omega)\right)-E_{N} \bar{g}\left(\bar{x}_{N}(\omega), \xi(\omega)\right)\right|\right. \\
& \left.+\left|E_{N} \bar{g}\left(\bar{x}_{N}(\omega), \xi(\omega)\right)-E \bar{g}(\bar{x}, \xi(\omega))\right|\right\},
\end{aligned}
$$

for all $\omega \in \Omega, N=1,2, \ldots$ and $E \bar{g}\left(\bar{x}_{N}(\omega), \xi(\omega)\right)=[E \bar{g}(x, \xi(\omega))]_{x=]_{N}(\omega)}$.
, However, now we can already see that the validity of (18) follows immediately from the last inequalities system and from the relations (17).

Proof of Theorem 5. As the proof of Theorem 5 is very similar to the proof of Theorem 4, we omit it. It is necessary to employ there the results of the paper [11] (Theorem 2 and the corresponding proof) and Lemma 4 instead of the results of the paper [10] and Lemma 3.

We have finished the proof of the assertions corresponding to the deterministic equivalent $I$. Now we shall deal with the assertions belonging to the deterministic equivalent II.

Proof of Theorem 7. The proof of the relation (24) is given in [13]. Since this proof is rather complicated and long we shall not repeat it here. However we shall verify carefully the validity of the relation (25). For this let $t>0$ fulfil the assumptions of Theorem 7. We define the set $\Omega_{t}$ by the relation

$$
\Omega_{t}=\left\{\omega \in \Omega: X_{N}(\alpha) \subset X(\alpha-t)\right\} .
$$

The following auxiliary assertion follows from [13].

Lemma 5. Let $\alpha \in(0,1), \delta>0$. If the assumptions $i$, ii are fulfilled and if $\left\{\xi^{k}(\omega)\right\}_{k=1}^{\infty}$ is a sequence of independent random vectors then for $t>0, d>0$ such that $d<\delta$,

$$
\frac{\sqrt{n}}{\lambda_{1}} \sqrt[4]{\frac{2 t}{v_{1}}}<\delta, \quad \vartheta_{2} \lambda_{2} d \sum_{i=1}^{\ell} \prod_{v \neq i} c_{v}<\frac{t}{3}
$$

then

$$
\begin{aligned}
& P\left\{\omega: X(\alpha+t) \subset X_{N}(\alpha) \subset X(\alpha-t)\right\} \\
& \quad \geqslant 1-2 m[X(\alpha, 2 \delta), d] \exp \left\{-N t^{2} / 18\right\} .
\end{aligned}
$$

Proof. It is proved in [13] (Lemma 5) that under our assumptions

$$
\begin{aligned}
& P\left\{\omega: X(\alpha+t) \subset X_{N}(\alpha) \subset X(\alpha-t)\right\} \\
& \quad \geqslant 1-\sum_{x^{\bullet} \in S(X(\alpha, 26), d)} P\left\{\omega: \left\lvert\, P_{N}\left(Z\left(x^{v}\right)-P\left(Z\left(x^{v}\right) \left\lvert\,>\frac{t}{3}\right.\right\} .\right.\right.\right.
\end{aligned}
$$

However now already the assertion of Lemma 5 follows immediately from the last inequality, Lemma 3 and the definition of the number $\bar{m}(X(\alpha, 2 \delta), d)$.

We can continue in the proof of Theorem 7.
According to Lemma 5 we obtain that

$$
P\left\{\omega: \omega \in \Omega-\Omega_{t}\right\} \leqslant 2 m[X(\alpha, 2 \delta), d] \exp \left\{-N t^{2} / 18\right\}
$$

and so also

$$
\begin{align*}
& P\left\{\omega:\left\|x_{N}(\alpha, \omega)-x(\alpha)\right\|^{2} \geqslant 4 \frac{t_{0} L}{\rho}\right\} \\
& \quad \leqslant 2 m[X(\alpha, 2 \delta), d] \exp \left\{-N t^{2} / 18\right\}  \tag{30}\\
& \quad+P\left\{\left[\omega:\left\|x_{N}(\alpha, \omega)-x(\alpha)\right\|^{2} \geqslant 4 \frac{t_{0} L}{\rho}\right] \cap \Omega_{1}\right\} .
\end{align*}
$$

Since

$$
\left\|x_{N}(\alpha, \omega)-x(\alpha)\right\|^{2} \leqslant 2\left\{\left\|x_{N}(\alpha, \omega)-x(\alpha-t)\right\|^{2}+\|x(\alpha)-x(\alpha-t)\|^{2}\right\}
$$

and since $E g(x, \xi(\omega))$ is a strongly convex with the parameter $\rho>0$ function and $X(\alpha)$ is a convex set [19], we obtain for $\omega \in \Omega_{t}$ successively

$$
\begin{align*}
\left\|x_{N}(\alpha, \omega)-x(\alpha)\right\|^{2} \leqslant & \left(\frac{4}{\rho}\right)\left\{\left|E g\left(x_{N}(\alpha, \omega), \xi(\omega)\right)-E g(x(\alpha-t), \xi(\omega))\right|\right. \\
& +|E g(x(\alpha), \xi(\omega))-E g(x(\alpha-t), \xi(\omega))|\} \\
\leqslant & \left(\frac{4}{\rho}\right)\left\{\left|E g\left(x_{N}(\alpha, \omega), \xi(\omega)\right)-E_{N} g\left(x_{N}(\alpha-t), \xi(\omega)\right)\right|\right. \\
& +\left|E_{N} g\left(x_{N}(\alpha, \omega), \xi(\omega)\right)-E g(x(\alpha) \xi(\omega))\right| \\
& +|E g(x(\alpha), \xi(\omega))-E g(x(\alpha-t), \xi(\omega))| \\
& +|E g(x(\alpha), \xi(\omega))-E g(x(\alpha-t), \xi(\omega))|\}, \tag{31}
\end{align*}
$$

where $\left.E g\left(x_{N}(\alpha, \omega), \xi(\omega)\right)=\mid E g(x, \xi(\omega))\right]_{x=x_{N}(\alpha, \omega)}$.
The next auxiliary assertion was proved in [13] too.
Lemma 6. Let $\alpha \in(0,1)$. If the assumptions i , ii are fulfilled then for $t>0$ the inequality

$$
\Delta[X(\alpha), X(\alpha-t)]<\frac{\sqrt{n}}{\lambda_{1}} \sqrt[2]{\left(\frac{2 t}{\vartheta_{1}}\right)}
$$

holds.
However according to this assertion and to the relations (24), (31) it is easy to see that the relation (25) will be proved if we verify the relation

$$
\begin{align*}
& P\left\{\omega \in \Omega_{t}:\left|E g\left(x_{N}(\alpha, \omega), \xi(\omega)\right)-E_{N} g\left(x_{N}(\alpha, \omega), \xi(\omega)\right)\right|\right. \\
& \left.\quad+\left|E_{N} g\left(x_{N}(\alpha, \omega), \xi(\omega)\right)-E g(x(\alpha), \xi(\omega))\right| \geqslant\left(\frac{t_{0} L}{2}\right)\right\}  \tag{32}\\
& \quad \leqslant 4 m[X(\alpha, 2 \delta), d] \exp \left[-N t^{2} / 18\right] \\
& \quad+4 m[X(\alpha, 2 \delta), d] \exp \left\{-N t_{0}^{2} L^{2} / 4 \cdot 18 M^{2}\right\} .
\end{align*}
$$

## However as

$$
\begin{aligned}
P\{\omega & \left.\in \Omega_{t}:\left|E g\left(x_{N}(\alpha, \omega), \xi(\omega)\right)-E_{N} g\left(x_{N}(\alpha, \omega), \xi(\omega)\right)\right| \geqslant\left(\frac{t_{0} L}{4}\right)\right\} \\
& \leqslant P\left\{\omega: \left\lvert\, E g\left(x_{N}(\alpha, \omega), \xi(\omega j)-E_{N} g\left(x_{N}(\alpha, \omega), \xi(\omega)\right) \left\lvert\, \geqslant\left(\frac{t_{0} L}{4}\right)\right.\right.\right.\right.
\end{aligned}
$$

$$
\text { for at least one } x \in X(\alpha, 2 \delta)\}
$$

and as $X\left(\alpha_{1} 2 \delta\right)$ is a compact set we see that the validity of the relation (32) follows immediately by Theorem 4 and the inequality (24).

Theorem 7 deal with the case of independent random samples. The $\phi$-mixing case is considered in Theorem 8 . Since the proof of Theorem 8 is yery similar to the proof of Theorem 7 we omit it. We remember here only that instead of the results of Theorem 4 in thi's case the results of Theorem 5 is employed.

Remark. A proof of measurability of the random vectors $\vec{x}_{N}(\omega), x_{N}(\alpha, \omega)$ is omited in this paper. But it follows from the paper [30].
5. Conclusion. The presented paper have dealt with convergence rate of the empirical estimates in stochastic programming problems. Former results on this topic are improved.

It is seen that the interval for $\beta$ fulfiling the relations (5), (6), (7), (8) are greater in simplest case, of course. Especially this interval is rather smaller in the case of deterministic equivalent II. This reality is evidently caused by new inaccuracy that arised by the approximation of the constraints set $X(\alpha)$. We can recognize this following the proof of the corresponding results and proofs. introduced in [13]. However this question will not be discussed more in this paper.

## REFERENCES

[1] Billingsley, P. (1968). Convergence of Probability Measure. J.Wiley \& Sons, New York.
[2] Dupačová, J. (1976). Experience in stochastic programming models. In A.Prékopa (Ed.), Survery of Math. Programming. Proc IX. Math. Progr. Symp., Akadémiai Kiadó, Budapest. pp. 95-105.
[3] Dupačová, J. (1987). Stochastic programming with incomplete information. A Survey of Results on Postoptimization and Sensivity Analysis. Optimization, 18(4), 507-532.
[4] Dupačová, J., and R.Wets (1988). Asymptotic behaviour of statistical estimators and optimal solutions of stochastic optimization problems. Annals of

Stat., 16(4), 1517-1549.
[5] Dupačová, J. (1988). On Nonnormal Asymptotic Behaviour of Optimal Solutions of Stochastic Programming Problems. The Parametric Case. WP-8819, IIASA, Laxenburg, Austria.
[6] Dupacova, J. (1990). Stability and sensitivity analyeis for stochastic programming. Annals of Operations Reseerch, 29, 115-142.
[7] Hoeffding, W. (1963). Probability inequalities for sums of bounded random variables. Journal of the Americ. Statist. Ass., 58(301), 13-30.
[8] Kall, P. (1976). Stochastic Linear Programming. Springer, Berlin-Heidel-berg-New York.
[9] Kan̆ková, V. (1977). Optimum solution of a stochastic optimization problem with unknown parameters. In Trans. of the Seventh Prague Conference 1974, Academia, Prague. pp. 239-244.
[10] Kan̆ková, V. (1978). An approximative solution of a stochastic optimization problem. In Trans. of the Eighth Prague Conference, Academia; Prague. pp. 349-353.
[11] Kañková, V. (1989). Empirical estimates in stochastic programming. In Trans. of the Tenth Prague Conference 1986, (Band B) Academia, Prague. pp. 21-28.
[12] Kaňková, V. (1989). Estimates in stochastic programming - chance constrained case. Problems of Control and Information Theory, 18(4), 251-260.
[13] Kanková, V. (1990). On the convergence rate of empirical estimates in chance constrained stochastic programming. Kybernetika, 26(6), 449-461.
[14] Kaňková, V. Stability in stochastic programming - the case of unknown location parameter. To appear in Kybernetika,
[15] Kasitskaya, E.I., and P.S.Knapov (1991). Convergence of empirical estimates in problems of stochastic optimization. Kibernetika, 112(2), 104-107.
[16] King, A.J. (1988). Asymptotic Distributions for Solutions in Stochastic Optimization and Generalized M-Estimation. WP-88-58, IIASA, Laxenburg.
[17] Norkin, V.I. (1989). Stability of Stochastic Optimization Models and Statistical Methods in Stochastic Programming. (from reports of International Institute of Applied System Analysis). Preprint, 89-53 Akad. Nauk Ukrain.: SSR Inst. Kibernet., Kiev. 25.pp. (ia Russian).
[18] Prékopa, A. (1973). On logarithmic cancave measures and functions. Acta Scientarium Mathematicarum Szeged, 34, 335-343.
[19] Prékopa, A. (1971). Stochastic programming models for inventory control and water storage problems. In Colhquia Mathematioa Societatis János Bolyai 7. Inventory Control and Water Storage, Györ Hungary.
\{20] Pṡeničnyj, B.N., and Yu.M.Danilin (1975). Numerical Methods in Optimal Problem. Nauka, Moskva (in Russian).
[21] Rọmisch, W., and A.Wakolbinger (1987). Obtaining convergence for approximates in stochastic programming. In J.Guddat (Ed.), Parametric Optimization and Related Topics, Akad. Verlag, Berlin. ,pp. 327-343.
[22] Römisch, W., and R.Schultz (1988). Distribution Sensitivity for a Chance Constrained Model of Optimal. Load Dispatch. Humb. Univ. Berlin, Sekt. Mathem., Preprint 198.
[23] Römisch, W., and R.Schultz (1989). Stability Analysis for Stochastic Program. Humb. Univ. Berlin, Sekt. Mathem., Preprint 242.
[24] Römisch, W., and R.Schultz (1991). Distribution sensitivity in stochastic "programming. Mathematical Programming, 50, 197-226.
[25] Salinetti, G. (1983). Approximations for chance constrained programming problems. Stochastics, 10, 157-179.
[26] Tamm, E. (1980). Inequalities for thè solutions of nonlinear programming problems depending on a random parameter.' Math. Operationsforsh. Statist. Ser. Optimization, 11(3), 487-407.
[27] Tamm, E. (1987). Approximation of a random solution in extremum problems. Kybernetika, 23(6), 483-488.
[28] Tarasenko, G.S. (1980). On the estimation of the convergence rate of the adaptive random search method. Problemy Slucajnogo Poiska, 8, 162-185. (in Russian).
[29] Vogel, S. (1988): Stability results for stochastic programming problems. Optimization, 19(2), 264-288.
[30] Vogel, S. On Stability in Multiobjective Programming - A. Stochastic Approach. To appeaf in Mathematical Programming.
[31] Wets, R. (1971)! A Stochastic Approach to the Solution of Stochastic Pro-' grams with (Convex) Simple Recourse. Research Report Univ. Kentucky, USA.
[32] Wets, R. (1990). Constrained Estimation. Consistency and Asymptotics. WP-90-075, IIASA, Laxenburg.
V. Kañková studied the Faculty of Mathematics and Physics of Charles University of Prague. She specialized in probability theory and mathematical statistics. After completion of the university studies she joined the Institute of Information Theory and Automation of the Czechoslovak Academy of Sciences where her research interests include mostly stochastic programming problems.
P. Lachout completed the Faculty of Mathematics and Physics of Charles University of Prague. He studied probability theory and mathematical statistics. Since 1986, he has worked in the Institute of Information Theory and Automation of the Czechoslovak Academy of Sciences. He is interested in probability theory especially in stochastic processes.

