# A Mathematical Analysis of an Age-Sex-Space-Structured Population Dynamics Model with Random Mating and Females' Pregnancy 

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#### Abstract

We discuss an age-sex-structured population dynamics deterministic model taking into account random mating of sexes, females' pregnancy and its dispersal in whole space. This model can be derived from the previous one (Skakauskas, 1995) describing migration mechanism by the general linear elliptic operator of second order and includes the male, single (nonfertilized) female and fertilized female subclasses. Using the method of the fundamental solution for the uniformly parabolic second-order differential operator with bounded Hölder continuous coefficients we prove the existence and uniqueness theorem for the classic solution of the Cauchy problem for this model. In the case where dispersal moduli of fertilized females are not depending on age of the mated male we analyze population growth and decay.


Key words: population dynamics, random mating, gestation of males, pregnancy, migration.

## 1. Introduction

In the paper (Skakauskas, 1994) we have developed a general deterministic model for an age-sex-structured population dynamics taking into account random mating of sexes without formation of permanent male-female couples, female's pregnancy, possible destruction of the fetus (abortion), and female's sterility periods after abortion and delivery. The population is divided into five components: one male and four female, the latter four being the single (nonfertilized) female, fertilized female, female from sterility period after abortion, and female from sterility one following delivery. Each sex has three age-grades: pre-reproductive, reproductive, and post-reproductive. It is assumed that for each sex the commencement of each grade as well as the duration of the gestation and female's sterility periods are independent of individuals or time. Latter, in (Skakauskas, 1995), we generalized this model for the spatially dispersing population in whole space. Spatial dispersal mechanism in this model is described by an integral operator.

In the present paper we simplify the model in (Skakauskas, 1995) by neglecting abortion and female's sterility periods, replace the integral describing operator migration by
the general linear elliptic differential one of second order and prove classical solvability of the initial problem for this model. The special case of the present model for the population dispersing in the whole space, where all vital rates of fertilized female are independent of age of mated partner, has been considered in (Skakauskas, 1997), and the existence and uniqueness theorems for the steady (i.e., time independent) and nonstationary cases have been proved.

This paper is organized as follows. In Section 3 we formulate the problem, Section 4 represents main hypotheses and results. In Section 5 we recall some classical results concerning unique solvability of the Cauchy problem for the linear differential parabolic operator of second order with parameter. Section 6 is devoted to proving the solvability theorem. In Sections 7 and 8 in the case where dispersal moduli of fertilized females are independent of age of mated males, we obtain upper estimates for population growth and extinction.

## 2. Notations

We follow the notations used in (Skakauskas, 1995):
$\tau_{1}, \tau_{2}, \tau_{3}$ : the ages of male, female, and embryo, respectively;
$t$ : time;
$E^{m}$ : Euclidean space (habitat of population) of dimension $m$;
$x=\left(x_{1}, x_{2}, \ldots, x_{m}\right)$ : the spatial position in $E^{m}$;
$u_{1}\left(x, t, \tau_{1}\right)$ : the age-space density of males at age $\tau_{1}$, location $x$ and time $t$;
$u_{2}\left(x, t, \tau_{2}\right)$ : the age-space density of single (nonfertilized) females at age $\tau_{2}$, location $x$ and time $t$;
$u_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right)$ : the age-space density of fertilized females at age $\tau_{2}$, position $x$ and time $t$ whose embryo is at age $\tau_{3}$ and that were fertilized by males at age $\tau_{1}$;
$p\left(x, t, \tau_{1}, \tau_{2}\right)$ : the density of probability to become fertilized for a female from the male-female pair formed of male at age $\tau_{1}$ and female at age $\tau_{2}$, at location $x$ and time $t$;
$\nu_{1}\left(x, t, \tau_{1}\right)$ (resp. $\nu_{2}\left(x, t, \tau_{2}\right)$ ): the death rate of males at age $\tau_{1}$ (resp. single females at age $\tau_{2}$ ), position $x$ and time $t$;
$\nu_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right)$ : the death rate of fertilized females at age $\tau_{2}$, position $x$ and time $t$ whose embryo is at age $\tau_{3}$ and that were fertilized by males at age $\tau_{1}$; ;
$X\left(u_{3}\right)\left(x, t, \tau_{2}\right)$ : the single female gain rate by the females which have had a delivery at age $\tau_{2}$, position $x$ and time $t$;
$Y\left(u_{1}\right)\left(x, t, \tau_{2}\right) u_{2}$ : the single female loss due to conception at age $\tau_{2}$, location $x$ and time $t$;
$\sigma_{1}=\left(\tau_{11}, \tau_{12}\right], 0<\tau_{11}<\tau_{12}<\infty$ : the female sexual activity interval, $\bar{\sigma}_{1}=$ $\left[\tau_{11}, \tau_{12}\right]$;
$\sigma_{3}=(0, T], 0<T<\infty$ : the female gestation interval, $\bar{\sigma}_{3}=[0, T] ;$
$\sigma_{2}\left(\tau_{3}\right)=\left(\tau_{21}+\tau_{3}, \tau_{22}+\tau_{3}\right], 0<\tau_{21}<\tau_{22}<\infty, \bar{\sigma}_{2}\left(\tau_{3}\right)=\left[\tau_{21}+\tau_{3}, \tau_{22}+\tau_{3}\right] ;$
$\sigma_{2}(0), \sigma_{2}(T)$ : the female fertilization and reproductivity intervals, respectively;
$n_{1}(x, t)$ : the spatial density of males with ages from $\sigma_{1}$;
$b_{1}\left(x, t, \tau_{1}, \tau_{2}\right)$ and $b_{2}\left(x, t, \tau_{1}, \tau_{2}\right)$ : the average numbers of male and female offspring, respectively, produced at time $t$ at the position $x$ by a fertilized female of characteristics $\left(\tau_{1}, \tau_{2}, T\right)$;
$u_{1}^{0}\left(x, \tau_{1}\right), u_{2}^{0}\left(x, \tau_{2}\right), u_{3}^{0}\left(x, \tau_{1}, \tau_{2}, \tau_{3}\right)$ : the initial distributions;
$\sigma=\sigma_{1} \times \sigma_{2}(T), \bar{\sigma}=\bar{\sigma}_{1} \times \bar{\sigma}_{2}(T), d \sigma=d \tau_{1} d \tau_{2} ;$
$\tau_{2}^{0}=0, \tau_{2}^{1}=\tau_{21}, \tau_{2}^{2}=\min \left(\tau_{21}+T, \tau_{22}\right), \tau_{2}^{3}=\max \left(\tau_{21}+T, \tau_{22}\right), \tau_{2}^{4}=\tau_{22}+T$,
$\tau_{2}^{5}=\infty$;
$I=(0, \infty), \bar{I}=[0, \infty), I_{4}=\left(\tau_{2}^{4}, \infty\right), I_{s}=\left(\tau_{2}^{s}, \tau_{2}^{s+1}\right], s=\overline{0,3} ;$
$I^{*}=\left(0, t^{*}\right], \bar{I}^{*}=\left[0, t^{*}\right], t^{*}<\infty ;$
$Q_{1}=\left\{\left(x, t, \tau_{1}\right) \in E^{m} \times I \times I\right\}, Q_{2}=\left\{\left(x, t, \tau_{2}\right) \in E^{m} \times I \times\left(I \backslash \bigcup_{s=1}^{4} \tau_{2}^{s}\right)\right\} ;$
$Q_{3}=\left\{\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right) \in E^{m} \times I \times \sigma_{1} \times \sigma_{2}\left(\tau_{3}\right) \times \sigma_{3}\right\} ;$
$\bar{Q}_{1}=\bar{Q}_{2}=E^{m} \times \bar{I} \times \bar{I}, \bar{Q}_{3}=E^{m} \times \bar{I} \times \bar{\sigma}_{1} \times \bar{\sigma}_{2}\left(\tau_{3}\right) \times \bar{\sigma}_{3} ;$
$\left[\left.u_{2}\right|_{\tau_{2}=\tau_{2}^{j}}\right]:$ the jump of function $u_{2}$ at the plane $\tau_{2}=\tau_{2}^{j}$;
$\widehat{D}_{1}=\partial / \partial t+\partial / \partial \tau_{1}, \widehat{D}_{2}=\partial / \partial t+\partial / \partial \tau_{2}, \widehat{D}_{3}=\widehat{D}_{2}+\partial / \partial \tau_{3} ;$
$D_{1}=\sqrt{2} \widetilde{D}_{1}, D_{2}=\sqrt{2} \widetilde{D}_{2}, D_{3}=\sqrt{3} \widetilde{D}_{3} ;$
$\widetilde{D}_{i}, i=1,2,3$ : the directional derivative in the positive direction of characteristics of the operator $\widehat{D}_{i}$;

$$
a_{i j}^{k}\left(x, t, \tau_{k}\right), a_{i}^{k}\left(x, t, \tau_{k}\right), k=1,2, a_{i j}^{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right), a_{i}^{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right), i, j=
$$

$\overline{1, m}$ : the space dispersal moduli of males $(k=1)$, single females $(k=2)$, and fertilized females;

$$
\begin{aligned}
& L_{k}\left(x, t, \tau_{k}\right)=\sum_{i, j=1}^{m} a_{i j}^{k} \partial^{2} / \partial x_{i} \partial x_{j}+\sum_{i=1}^{m} a_{i}^{k} \partial / \partial x_{i}-\nu_{k}\left(x, t, \tau_{k}\right), \quad k=1,2 \\
& L_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right)=\sum_{i, j=1}^{m} a_{i j}^{3} \partial^{2} / \partial x_{i} \partial x_{j}+\sum_{i=1}^{m} a_{i}^{3} \partial / \partial x_{i}-\nu_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right)
\end{aligned}
$$

$C^{0}\left(E^{m} \times J_{1} \times \ldots \times J_{s}\right), J_{s}=\left(J_{s 1}, J_{s 2}\right), J_{s 1}<J_{s 2}<\infty$ : the Banach space of bounded continuous in $E^{m} \times J_{1} \times \ldots \times J_{s}$ functions $f\left(x, \xi_{1}, \xi_{2}, \ldots, \xi_{s}\right)$;
$C^{\alpha, 0, \ldots, 0}\left(E^{m} \times J_{1} \times \ldots \times J_{s}\right)$ : the Banach space of functions $f\left(x, \xi_{1}, \xi_{2}, \ldots, \xi_{s}\right)$ belonging to $C^{0}\left(E^{m} \times J_{1} \times \ldots \times J_{s}\right)$, which are Hölder continuous in $\left(E^{m} \times J_{1} \times \ldots \times J_{s}\right)$ with exponent $\alpha \in(0,1)$ in $x$ uniformly with respect to $\left(\xi_{1}, \xi_{2}, \ldots, \xi_{s}\right)$, i.e., having the finite Holder seminorm with respect to $x$ (see [2]).
$C^{\alpha, \alpha / 2, \ldots, \alpha / 2}\left(E^{m} \times J_{1} \times \ldots \times J_{s}\right)$ : the Banach space of functions $f\left(x, \xi_{1}, \xi_{2}, \ldots, \xi_{s}\right)$ belonging to $C^{0}\left(E^{m} \times J_{1} \times \ldots \times J_{s}\right)$, which are Hölder continuos in $\left(E^{m} \times J_{1} \times \ldots \times J_{s}\right)$ with exponent $\alpha \in(0,1)$ in $x$ and $\alpha / 2$ in $\xi_{k}, k=\overline{1, s}$, i.e., having the finite Hölder seminorm with respect to $x, \xi_{1}, \ldots, \xi_{s}$.
$C^{1,0, \ldots, 0}\left(E^{m} \times J_{1} \times \ldots \times J_{s}\right)$ : the Banach space of functions $f\left(x, \xi_{1}, \xi_{2}, \ldots, \xi_{s}\right)$ such that $\partial f / \partial x_{i} \in C^{0}\left(E^{m} \times J_{1} \times \ldots \times J_{s}\right), i=\overline{1, m}$.

For more details concerning population densities and vital rates we refer the reader to (Skakauskas, 1995).

## 3. Problem Formulation

The model to be discussed in this paper consists of the following nonlinear system of integrodifferential equations for $u_{1}, u_{2}, u_{3}$,

$$
\begin{align*}
& \left(D_{1}-L_{1}\right) u_{1}=0 \quad \text { in } Q_{1},  \tag{1}\\
& \left(D_{2}-L_{2}\right) u_{2}=X\left(u_{3}\right)-u_{2} Y\left(u_{1}\right)  \tag{2}\\
& Y\left(u_{1}\right)= \begin{cases}0, & \text { in } Q_{2}, \\
n_{1}^{-1} \int_{\sigma_{1}} p u_{1} d \tau_{1}, n_{1}=\int_{\sigma_{1}} u_{1} d \tau_{1}, & \tau_{2} \in \sigma_{2}(0),\end{cases}  \tag{3}\\
& X\left(u_{3}\right)= \begin{cases}0, & \tau_{2} \notin \sigma_{2}(T), \\
\left.\int_{\sigma_{1}} u_{3}\right|_{\tau_{3}=T} d \tau_{1}, & \tau_{2} \in \sigma_{2}(T),\end{cases}  \tag{4}\\
& \left(D_{3}-L_{3}\right) u_{3}=0  \tag{5}\\
& \text { in } Q_{3},
\end{align*}
$$

which supplemented with the conditions

$$
\begin{align*}
& \left.u_{k}\right|_{t=0}=u_{k}^{0}, \quad k=1,2 \quad \text { in } E^{m} \times I, \\
& \left.u_{3}\right|_{t=0}=u_{3}^{0} \quad \text { in } E^{m} \times \sigma_{1} \times \sigma_{2}\left(\tau_{3}\right) \times \sigma_{3},  \tag{6}\\
& \left.u_{k}\right|_{\tau_{k}=0}=\left.\int_{\sigma} b_{k} u_{3}\right|_{\tau_{3}=T} d \sigma, \quad k=1,2 \quad \text { in } E^{m} \times I,  \tag{7}\\
& \left.u_{3}\right|_{\tau_{3}=0}=p u_{1} u_{2} / n_{1} \quad \text { in } E^{m} \times I \times \sigma_{1} \times \sigma_{2}(0),  \tag{8}\\
& {\left[\left.u_{2}\right|_{\tau_{2}=\tau_{2}^{s}}\right]=0, \quad s=\overline{1,4} \quad \text { in } E^{m} \times I,} \tag{9}
\end{align*}
$$

describes evolution of the population with dispersal in whole space. In addition we assume that the initial distributions $u_{1}^{0}, u_{2}^{0}, u_{3}^{0}$ satisfy the following compatibility conditions

$$
\begin{align*}
& \left.u_{k}^{0}\right|_{\tau_{k}=0}=\left.\left.\int_{\sigma} b_{k}\right|_{t=0} u_{3}^{0}\right|_{\tau_{3}=T} d \sigma, \quad k=1,2 \quad \text { in } E^{m}, \\
& \left.u_{3}^{0}\right|_{\tau_{3}=0}=\left.p\right|_{t=0} u_{1}^{0} u_{2}^{0} / \int_{\sigma_{1}} u_{1}^{0} d \tau_{1} \quad \text { in } E^{m} \times \sigma_{1} \times \sigma_{2}(0) . \tag{10}
\end{align*}
$$

As it follows from the foregoing, given functions $\nu_{1}, \nu_{2}, \nu_{3}, p, b_{1}, b_{2}, u_{1}^{0}, u_{2}^{0}, u_{3}^{0}$ and the unknown ones $u_{1}, u_{2}, u_{3}$ must be positive-valued, otherwise they have no biological significance. Our purpose is to find $u_{1}, u_{2}, u_{3}$.

Observe that replacing $L_{k} u_{k}, k=1,2$ and $L_{3} u_{3}$ in (1)-(10) by

$$
\int_{E^{m}} q_{k}\left(x, t, \tau_{k}, \xi\right) u_{k}\left(\xi, t, \tau_{k}\right) d \xi-u_{k}\left(x, t, \tau_{k}\right) \int_{E^{m}} q_{k}\left(\xi, t, \tau_{k}, x\right) d \xi, \quad k=1,2
$$

and

$$
\begin{aligned}
& \int_{E^{m}} q_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}, \xi\right) u_{3}\left(\xi, t, \tau_{1}, \tau_{2}, \tau_{3}\right) d \xi \\
& \quad-u_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right) \int_{E^{m}} q_{3}\left(\xi, t, \tau_{1}, \tau_{2}, \tau_{3}, x\right) d \xi
\end{aligned}
$$

respectively, with given nonnegative $q_{1}, q_{2}, q_{3}$ we obtain a model analyzed in (Skakauskas, 1995).

## 4. Hypotheses and Main Results

Unless otherwise stated, the assumptions listed in this section hold throughout the paper:
$\left(\mathrm{H}_{1}\right) p\left(x, t, \tau_{1}, \tau_{2}\right) \in C^{1,0,0,0}\left(E^{m} \times \bar{I} \times \bar{\sigma}_{1} \times \bar{\sigma}_{2}(0)\right)$ is a nonnegative function with a compact support in $x\left(\operatorname{supp} p\left(\cdot, t, \tau_{1}, \tau_{2}\right)\right)$ and such that $p t^{-1 / 2} \in C^{0,0,0,0}\left(E^{m} \times[0, \varepsilon] \times \bar{\sigma}_{1} \times \bar{\sigma}_{2}(0)\right)$ for any small $\varepsilon>0 ;$
$\left(\mathrm{H}_{2}\right) b_{k}\left(x, t, \tau_{1}, \tau_{2}\right) \in C^{0}\left(E^{m} \times \bar{I} \times \bar{\sigma}_{1} \times \bar{\sigma}_{2}(T)\right), k=1,2$ are nonnegative functions;
$\left(\mathrm{H}_{3}\right) \nu_{k}\left(x, t, \tau_{k}\right) \in C^{\alpha, 0,0}\left(\bar{Q}_{k}\right), k=1,2, \nu_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right) \in C^{\alpha, 0,0,0,0}\left(\bar{Q}_{3}\right)$ are nonnegative functions;
$\left(\mathrm{H}_{4}\right) a_{i j}^{k}\left(x, t, \tau_{k}\right) \in C^{\alpha, \alpha / 2, \alpha / 2}\left(\bar{Q}_{k}\right), a_{i}^{k}\left(x, t, \tau_{k}\right) \in C^{\alpha, 0,0}\left(\bar{Q}_{k}\right), k=1,2$,
$i, j=\overline{1, m}$ and $a_{i j}^{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right) \in C^{\alpha, \alpha / 2, \alpha / 2, \alpha / 2, \alpha / 2}\left(\bar{Q}_{3}\right), a_{i}^{3}\left(x, t, \tau_{1} \tau_{2}, \tau_{3}\right) \in$
$C^{\alpha, 0,0,0,0}\left(\bar{Q}_{3}\right), i=\overline{1, m}$ are such that operators $L_{1}, L_{2}, L_{3}$ are uniformly elliptic (see Garoni and Menaldi, 1992; Ladyzhenskaya et al., 1967);
$\left(\mathrm{H}_{5}\right) u_{1}^{0}\left(x, \tau_{1}\right) \in C^{0}\left(E^{m} \times \bar{I}\right)$ is positive and $u_{2}^{0}\left(x, \tau_{2}\right) \in C^{0}\left(E^{m} \times \bar{I}\right)$, $u_{3}^{0}\left(x, \tau_{1}, \tau_{2}, \tau_{3}\right) \in C^{0}\left(E^{m} \times \bar{\sigma}_{1} \times \bar{\sigma}_{2}\left(\tau_{3}\right) \times \bar{\sigma}_{3}\right)$ are nonnegative functions verifying (10).

Now we list theorems for solvability of model (1)-(10), population growth and its decay which will be proved in Sections 6 and 7.

Theorem 1. Under the hypotheses $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{5}\right)$ problem (1)-(10) has for $t \in \bar{I}^{*}$ a unique nonnegative classic solution (see Garoni and Menaldi, 1992; Ladyzhenskaya et al., 1967) such that $u_{1} \in C^{0}\left(E^{m} \times \bar{I}^{*} \times \bar{I}\right), u_{2} \in C^{0}\left(E^{m} \times \bar{I}^{*} \times \bar{I}\right), u_{3} \in C^{0}\left(E^{m} \times \bar{I}^{*} \times \bar{\sigma}_{1} \times\right.$ $\left.\bar{\sigma}_{2}\left(\tau_{3}\right) \times \bar{\sigma}_{3}\right)$.

Let us introduce the following notions

$$
\begin{aligned}
& \widehat{b}=\max \left\{\int_{\sigma_{2}(T)} \sup _{E^{m} \times \bar{I} \times \bar{\sigma}_{1}} b_{1} d \tau_{2}, \int_{\sigma_{2}(T)} \sup _{E^{m} \times \bar{I} \times \bar{\sigma}_{1}} b_{2} d \tau_{2}\right\}, \\
& \widehat{p}=\sup _{E^{m} \times \bar{I} \times \bar{\sigma}_{1} \times \bar{\sigma}_{2}(0)} p, \\
& \widehat{u}=\max \left\{\sup _{E^{m} \times \bar{I}} u_{1}^{0}, \sup _{E^{m} \times \bar{I}} u_{2}^{0}\right\}, \quad \widehat{u}_{3}=\left.\sup _{E^{m} \times \bar{\sigma}_{2}(T)} \int_{\sigma_{1}} u_{3}^{0}\right|_{\tau_{3}=T} d \tau_{1} . \\
& \widetilde{\nu}_{2}=\inf _{E^{m} \times \bar{I} \times\left(\bar{I}_{2} \cup \bar{I}_{3}\right)} \nu_{2}, \\
& Q_{*}^{3}=\left\{\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right): x \in E^{m}, 0<t \leqslant \tau_{3}, \tau_{1} \in \sigma_{1}, \tau_{2} \in \sigma_{2}\left(\tau_{3}\right), \tau_{3} \in \sigma_{3}\right\}, \\
& Q^{3 *}=\left\{\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right): x \in E^{m}, t>\tau_{3}, \tau_{1} \in \sigma_{1}, \tau_{2} \in \sigma_{2}\left(\tau_{3}\right), \tau_{3} \in \sigma_{3}\right\}
\end{aligned}
$$

Theorem 2. Let $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{5}\right)$ hold, assume that $a_{i j}^{3}, a_{i}^{3}, i, j=\overline{1, m}$ are independent of $\tau_{1}$, and let $\widetilde{\nu}_{2}>0$.

Then
(i) $\int_{\sigma_{1}} u_{3} d \tau_{1} \leqslant \begin{cases}\widehat{u}_{3} & \text { in } Q_{3 *}, \\ \widehat{p} \sup _{y \in E^{m}} u_{2}\left(y, t-\tau_{3}, \tau_{2}-\tau_{3}\right) & \text { in } Q_{3}^{*} \quad \text { for } t-\tau_{3} \in \bar{I}^{*},\end{cases}$
(ii) $u_{k} \leqslant \delta \gamma^{s} \widehat{u} \quad$ for $t \in(s T,(s+1) T] \cap\left[0, t^{*}\right], x \in E^{m}, \tau_{k} \in \bar{I}$,
with $s=0,1, \ldots, k=1,2$, and $\gamma=\max \left(\widehat{b} \widehat{p}, 1, \widehat{p} / \widetilde{\nu}_{2}\right), \delta=\max \left(\widehat{b} \widehat{u}_{3} / \widehat{u}, 1, \widehat{u}_{3} / \widehat{u} \widetilde{\nu}_{2}\right)$ (or more roughly $u_{k} \leqslant \delta \widehat{u} \gamma^{t / T}$ ).

Define

$$
\begin{aligned}
& q=\widehat{b} \widehat{u}_{3} / \widehat{u}, \quad \widetilde{\nu}=\min \left(\overline{\inf }_{1} \nu_{1}, \quad \inf _{\bar{Q}_{2}} \nu_{2}\right) \\
& \omega_{0}=\left\{(x, t, \xi): x \in E^{m}, \quad 0 \leqslant t \leqslant \xi, \xi \in \bar{I}\right\} \\
& \omega_{s}=\left\{(x, t, \xi): x \in E^{m}, \quad(s-1) \tau_{k}^{4}<t-\xi \leqslant s \tau_{2}^{k}, t \leqslant t^{*}, \xi \in \bar{I}\right\}, \\
& \quad s=1,2 \ldots
\end{aligned}
$$

Theorem 3. Assume the hypotheses of Theorem 2 hold and let $\widehat{b} \widehat{p} \leqslant q \leqslant \min (1, \widetilde{\nu} \widehat{b})$, $\widetilde{\nu}>0$. Then:
(i) $\int_{\sigma_{1}} u_{3} d \tau_{1} \leqslant \begin{cases}\widehat{u}_{3} & \text { in } Q_{3 *}, \\ \hat{p}_{\sup }^{y \in E^{m}} \\ u_{2}\left(y, t-\tau_{3}, \tau_{2}-\tau_{3}\right) & \text { in } Q_{3}^{*} \text { for } t-\tau_{3} \in \bar{I}^{*},\end{cases}$
(ii) $\max \left\{\sup _{\omega_{s}} u_{1}, \sup _{\omega_{s}} u_{2}\right\} \leqslant \widehat{u} q^{s}$.

Corollary 1. Let assumptions of Theorem 3 hold. If $q<1$, then population vanishes as $t$ increases.

## 5. Some Properties of Parabolic Operators of Second Order

In this section we collect some classical results concerning the solvability and uniqueness of the Cauchy problem for the linear differential parabolic operator of second order (see Garoni and Menaldi, 1992; Ladyzhenskaya et al., 1967).

Lemma 1. Let

$$
\Lambda(x, t, \beta)=\partial / \partial t-\sum_{i, j=1}^{m} b_{i j} \partial^{2} / \partial x_{i} \partial x_{j}-\sum_{i=1}^{m} \widetilde{b}_{i} \partial / \partial x_{i}+b_{0}
$$

be a uniformly parabolic operator depending on a parameter $\beta \in J=\left[\beta_{1}, \beta_{2}\right]$, $\beta_{1}<$ $\beta_{2}<\infty$ with coefficients satisfying the following conditions

$$
\begin{aligned}
& b_{i j}(x, t, \beta) \in C^{\alpha, \alpha / 2,0}\left(E^{m} \times \bar{I}^{*} \times J\right), \quad i, j=\overline{1, m}, \\
& \widetilde{b}_{i}(x, t, \beta) \in C^{\alpha, 0,0}\left(E^{m} \times \bar{I}^{*} \times J\right), \quad i=\overline{0, m}
\end{aligned}
$$

and assume that

$$
\begin{aligned}
& 0<u^{0}(x, \beta) \in C^{0}\left(E^{m} \times J\right) \\
& 0<f(x, t, \beta) \in C^{\alpha, 0,0}\left(E^{m} \times \bar{I}^{*} \times J\right), \quad 0<\alpha<1
\end{aligned}
$$

Then problem

$$
\begin{align*}
& \Lambda u=f \quad \text { in } E^{m} \times \bar{I}^{*} \times J \\
& u(x, 0, \beta)=u^{0} \quad \text { in } E^{m} \times J \tag{11}
\end{align*}
$$

has a unique positive in $E^{m} \times \bar{I}^{*} \times$ J classic solution (see Garoni and Menaldi, 1992)

$$
\begin{align*}
u(x, t, \beta)= & \int_{E^{m}} \Gamma(x, t ; y, 0 ; \beta) u^{0}(y, \beta) d y \\
& +\int_{0}^{t} d \tau \int_{E^{m}} \Gamma(x, t ; y, \tau ; \beta) f(y, \tau, \beta) d y \tag{12}
\end{align*}
$$

where $\Gamma(x, t ; y, \tau ; \beta)$ is the fundamental solution of the operator $\Lambda(x, t, \beta)$.
Lemma 2 (The comparison principle (see Friedman, 1968)). Assume $b_{0}^{\prime}, b_{0}^{\prime \prime}, f^{\prime}, f^{\prime \prime}$ and $u^{0^{\prime}}, u^{0^{\prime \prime}}$ verify $0 \leqslant b_{0}^{\prime \prime} \leqslant b_{0}^{\prime}, 0 \leqslant f^{\prime} \leqslant f^{\prime \prime}$ and $u^{0^{\prime}} \leqslant u^{0^{\prime \prime}}$ in $E^{m} \times \bar{I}^{*} \times \bar{J}$ and
$E^{m} \times \bar{J}$, respectively. Then the corresponding solutions of problem (11) are such that $0 \leqslant u^{\prime} \leqslant u^{\prime \prime}$.

REMARK 1. Let $u^{0}, \Lambda(x, t, \beta)$ and its coefficients be as in Lemma 1. Then the conclusion of Lemma 1 holds true for $f$ verifying

$$
f(x, t, \beta) \in C^{0}\left(E^{m} \times \bar{I}^{*} \times \bar{J}\right), \quad|f(x, t, \beta)-f(y, t, \beta)| \leqslant \kappa t^{-\gamma}|x-y|^{\alpha}
$$

with $\kappa$ a constant and constant $\gamma \in(0,1)$.
The proof is the same as that of Lemma 1 in (Garoni and Menaldi, 1992) and based on the estimate

$$
\begin{aligned}
& \left|\int_{E^{m}} F(x, t ; y, \tau ; \beta) f(y, \tau, \beta) d y\right| \leqslant \kappa_{1}(t-\tau)^{-(2-\alpha) / 2} \tau^{-\gamma} \\
& \quad \text { for } F=\partial^{2} \Gamma / \partial x_{i} \partial x_{j}, \quad \partial \Gamma / \partial t
\end{aligned}
$$

which can be established by using the following inequality given in (Garoni and Menaldi, 1992; Ladyzhenskaya et al., 1967)

$$
\begin{gathered}
\left|\int_{E^{m}} F(x-y, y, t, \tau, \beta) d y\right| \leqslant \kappa_{1}(t-\tau)^{-(2-\alpha) / 2} \\
\quad \text { for } F=\partial^{2} \Gamma_{0} / \partial x_{i} \partial x_{j}, \quad \partial \Gamma_{0} / \partial t
\end{gathered}
$$

where $\kappa_{1}$ is a constant and $\Gamma_{0}$ signifies the parametrix

$$
\begin{aligned}
\Gamma_{0}(x-y, y, t & , \tau, \beta)=\left\{[4 \pi(t-\tau)]^{m / 2}(\operatorname{det} B(y, \tau))^{1 / 2}\right\}^{-1} \\
& \times \exp \left\{-\{4(t-\tau)\}^{-1} \sum_{i, j=1}^{m} B^{i j}(y, \tau)\left(x_{i}-y_{i}\right)\left(x_{j}-y_{j}\right)\right\}
\end{aligned}
$$

$B$ means the matrix with elements $b_{i j}(x, t, \beta), B^{-1}$ its inverse with elements $B^{i j}$.
We can also prove the estimate

$$
\begin{align*}
& \left|\int_{E^{m}}\left\{\Gamma(x, t ; y, \tau ; \beta)-\Gamma\left(x^{\prime}, t ; y, \tau ; \beta\right)\right\} f(y, \xi, \beta) d y\right| \\
& \quad \leqslant \kappa_{1}\left|x-x^{\prime}\right|(t-\tau)^{-1 / 2} \tag{13}
\end{align*}
$$

for $f \in C^{0}\left(E^{m} \times \bar{I}^{*} \times J\right)$, where $\kappa_{1}$ is a constant.
REMARK 2. Under the hypotheses of Remark $1, u \in C^{0}\left(E^{m} \times \bar{I}^{*} \times J\right)$.

The proof is based on the estimate

$$
\begin{align*}
& \left|\Gamma\left(x, t ; y, \tau ; \beta^{\prime \prime}\right)-\Gamma\left(x, t ; y, \tau ; \beta^{\prime}\right)\right| \\
& \quad<\varepsilon c(t-\tau)^{-m / 2} \exp \left\{-C|x-y|^{2} /(t-\tau)\right\} \tag{14}
\end{align*}
$$

for every $\varepsilon>0$ and sufficiently small $\left|\beta^{\prime \prime}-\beta^{\prime}\right|$, where $c$ and $C$ are two positive constants. This estimate can be proved by parametrix method, used in (Ladyzhenskaya et al., 1967) for construction of $\Gamma(x, t ; y, \tau ; \beta)$, as follows. According to Ladyzhenskaya et al. (1967) we have

$$
\begin{aligned}
\Gamma(x, t ; y, \tau ; \beta)= & \Gamma_{0}(x-y, y, t, \tau, \beta) \\
& +\int_{\tau}^{t} d \lambda \int_{E^{m}} \Gamma_{0}(x-\xi, \xi, t, \lambda, \beta) R(\xi, \lambda ; y, \tau ; \beta) d \xi \\
R(x, t ; \xi, \tau ; \beta)+ & \int_{\tau}^{t} d \lambda \int_{E^{m}} K(x, t ; y, \lambda ; \beta) R(y, \lambda ; \xi, \tau ; \beta) d y \\
& +K(x, t ; \xi, \tau ; \beta)=0 \\
K(x, t ; y, \lambda ; \beta)= & \sum_{i, j=1}^{m}\left(b_{i j}(y, \lambda, \beta)-b_{i j}(x, t, \beta)\right) \frac{\partial^{2}}{\partial x_{i} \partial x_{j}} \Gamma_{0}(x-y, y, t, \lambda, \beta) \\
& +\left\{-\sum_{i=1}^{m} b_{i}(x, t, \beta) \partial / \partial x_{i}+b_{0}(x, t, \beta)\right\} \Gamma_{0}(x-y, y, t, \lambda, \beta) \\
|K(x, t ; y, \tau ; \beta)| \leqslant & c(t-\tau)^{-(m+2-\alpha) / 2} \exp \left\{-C|x-y|^{2} /(t-\tau)\right\} \\
|R(x, t ; \xi, \tau ; \beta)| \leqslant & c(t-\tau)^{-(m+2-\alpha) / 2} \exp \left\{-C|x-\xi|^{2} /(t-\tau)\right\} \\
|\Gamma(x, t ; \xi, \tau ; \beta)| \leqslant & c(t-\tau)^{-m / 2} \exp \left\{-C|x-\xi|^{2} /(t-\tau)\right\}
\end{aligned}
$$

Letting

$$
g\left(x, \xi, t, \tau, \beta^{\prime \prime}, \beta^{\prime}\right)=R\left(x, t ; \xi, \tau ; \beta^{\prime \prime}\right)-R\left(x, t ; \xi, \tau ; \beta^{\prime}\right),
$$

we obtain

$$
\begin{aligned}
& g\left(x, \xi, t, \tau, \beta^{\prime \prime}, \beta^{\prime}\right)+\int_{\tau}^{t} d \lambda \int_{E^{m}} K\left(x, t ; y, \lambda ; \beta^{\prime \prime}\right) g\left(y, \xi, \lambda, \tau, \beta^{\prime \prime}, \beta^{\prime}\right) d y \\
& \quad+\int_{\tau}^{t} d \lambda \int_{E^{m}}\left(K\left(x, t ; y, \lambda ; \beta^{\prime \prime}\right)-K\left(x, t ; y, \lambda ; \beta^{\prime}\right)\right) R\left(y, \lambda ; \xi, \tau ; \beta^{\prime}\right) d y \\
& \quad+K\left(x, t ; \xi, \tau ; \beta^{\prime \prime}\right)-K\left(x, t ; \xi, \tau ; \beta^{\prime}\right)=0
\end{aligned}
$$

which by

$$
\begin{aligned}
& \mid \Gamma_{0}\left(x-y, y, t, \tau, \beta^{\prime \prime}\right)-\Gamma_{0}\left(x-y, y, t, \tau, \beta^{\prime} \mid\right. \\
& \quad \leqslant \varepsilon_{1} c(t-\tau)^{-m / 2} \exp \left\{-C|x-y|^{2} /(t-\tau)\right\}
\end{aligned}
$$

and

$$
\begin{aligned}
& \left|K\left(x, t ; y, \lambda ; \beta^{\prime \prime}\right)-K\left(x, t ; y, \lambda ; \beta^{\prime}\right)\right| \\
& \quad \leqslant \varepsilon_{1}(t-\lambda)^{-(m+2-\alpha) / 2} \exp \left\{-C|x-y|^{2} /(t-\lambda)\right\}
\end{aligned}
$$

yields

$$
\left|g\left(x, \xi, t, \tau, \beta^{\prime \prime}, \beta^{\prime}\right)\right| \leqslant \varepsilon_{1} c(t-\tau)^{-(m+2-\alpha) / 2} \exp \left\{-C|x-\xi|^{2} /(t-\tau)\right\}
$$

for every $\varepsilon_{1}>0$ and sufficiently small $\left|\beta^{\prime \prime}-\beta^{\prime}\right|$. Combining these estimates proves (14) which, by (12) and due to continuity of $u$ for fixed value of parameter, enables us to estimate difference $u\left(x^{\prime \prime}, t^{\prime \prime}, \beta^{\prime \prime}\right)-u\left(x^{\prime}, t^{\prime}, \beta^{\prime \prime}\right)+u\left(x^{\prime}, t^{\prime}, \beta^{\prime \prime}\right)-u\left(x^{\prime}, t^{\prime}, \beta^{\prime}\right)$. This ends the proof of Remark 2.

## 6. Proof of Theorem 1

Now we are in position to prove Theorem 1. We limit ourselves to the case of multiple deliveries including overlapping between successive generations, i.e., $T<\tau_{22}-\tau_{21}$, $\tau_{2}^{2}=\tau_{21}+T, \tau_{3}^{2}=\tau_{22}$. The opposite case can be considered by similar argument.

Set

$$
\begin{aligned}
& Q_{1}=Q_{*}^{1} \cup Q^{1 *}, \\
& E^{m} \times I \times I=\cup_{s=0}^{4} Q_{k}^{2}, \quad Q_{k}^{2}=E^{m} \times I \times I_{k}=Q_{k *}^{2} \cup Q_{k}^{2 *}, \quad k=\overline{0,4}, \\
& Q_{3}=Q_{*}^{3} \cup Q^{3 *}
\end{aligned}
$$

where

$$
\begin{aligned}
& Q_{*}^{1}=\left\{\left(x, t, \tau_{1}\right): x \in E^{m}, 0<t \leqslant \tau_{1}, \tau_{1} \in I\right\} \\
& Q^{1 *}=\left\{\left(x, t, \tau_{1}\right): x \in E^{m}, t>\tau_{1}, \tau_{1} \in I\right\} \\
& Q_{k *}^{2}=\left\{\left(x, t, \tau_{2}\right): x \in E^{m}, 0<t \leqslant \tau_{2}-\tau_{2}^{k}, \tau_{2} \in I_{k}\right\}, \\
& Q_{k}^{2 *}=\left\{\left(x, t, \tau_{2}\right): x \in E^{m}, t>\tau_{2}-\tau_{2}^{k}, \tau_{2} \in I_{k}\right\} \\
& Q_{*}^{3}=\left\{\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right): x \in E^{m}, 0<t \leqslant \tau_{3}, \tau_{1} \in \sigma_{1}, \tau_{2} \in \sigma_{2}\left(\tau_{3}\right), \tau_{3} \in \sigma_{3}\right\}, \\
& Q^{3 *}=\left\{\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right): x \in E^{m}, t>\tau_{3}, \tau_{1} \in \sigma_{1}, \tau_{2} \in \sigma_{2}\left(\tau_{3}\right), \tau_{3} \in \sigma_{3}\right\}
\end{aligned}
$$

Let $\tau_{1}=t+\eta_{1}$ and $\tau_{2}=t+\eta_{2}$ be characteristics of the operators $\widehat{D}_{1}$ and $\widehat{D}_{2}$, respectively, and assume that $\tau_{2}=t+\eta_{3}, \tau_{3}=t+\eta_{4}$ mean the characteristics of $\widehat{D}_{3}$. Here $\eta_{1}, \eta_{2}, \eta_{3}, \eta_{4}$ denote parameters of the characteristics. Letting

$$
\begin{aligned}
& L_{1}\left(x, t, t+\eta_{1}\right)=L_{1 *}\left(x, t, \eta_{1}\right), \quad u_{1}\left(x, t, t+\eta_{1}\right)=u_{1 *}\left(x, t, \eta_{1}\right) \quad \text { in } Q_{*}^{1}, \\
& L_{1}\left(x, \tau_{1}-\eta_{1}, \tau_{1}\right)=L_{1}^{*}\left(x, \tau_{1},-\eta_{1}\right), \\
& u_{1}\left(x, \tau_{1}-\eta_{1}, \tau_{1}\right)=u_{1}^{*}\left(x, \tau_{1},-\eta_{1}\right) \quad \text { in } Q^{1 *}, \\
& L_{2}\left(x, t, t+\eta_{2}\right)=L_{2 *}\left(x, t, \eta_{2}\right), \quad u_{2}\left(x, t, t+\eta_{2}\right)=u_{2 *}\left(x, t, \eta_{2}\right), \\
& Y\left(x, t, t+\eta_{2}\right)=Y_{*}\left(x, t, \eta_{2}\right), \quad X\left(x, t, t+\eta_{2}\right)=X_{*}\left(x, t, \eta_{2}\right) \quad \text { in }{\underset{k=0}{4} Q_{k *}^{2},}_{L_{2}\left(x, \tau_{2}-\eta_{2}, \tau_{2}\right)=L_{2}^{*}\left(x, \tau_{2},-\eta_{2}\right), \quad u_{2}\left(x, \tau_{2}-\eta_{2}, \tau_{2}\right)=u_{2}^{*}\left(x, \tau_{2},-\eta_{2}\right),}^{Y\left(x, \tau_{2}-\eta_{2}, \tau_{2}\right)=Y^{*}\left(x, \tau_{2},-\eta_{2}\right),} \\
& X\left(x, \tau_{2}-\eta_{2}, \tau_{2}\right)=X^{*}\left(x, \tau_{2},-\eta_{2}\right) \quad \text { in } \bigcup_{k=0}^{4} Q_{k}^{2 *}, \\
& L_{3}\left(x, t, \tau_{1}, t+\eta_{3}, t+\eta_{4}\right)=L_{3 *}\left(x, t, \tau_{1}, \eta_{3}, \eta_{4}\right), \\
& u_{3}\left(x, t, \tau_{1}, t+\eta_{3}, t+\eta_{4}\right)=u_{3 *}\left(x, t, \tau_{1}, \eta_{3}, \eta_{4}\right) \quad \text { in } Q_{*}^{3}, \\
& L_{3}\left(x, \tau_{3}-\eta_{4}, \tau_{1}, \tau_{3}+\eta_{3}-\eta_{4}, \tau_{3}\right)=L_{3}^{*}\left(x, \tau_{3}, \tau_{1},-\eta_{4}, \eta_{3}-\eta_{4}\right), \\
& \quad u_{3}\left(x, \tau_{3}-\eta_{4}, \tau_{1}, \tau_{3}+\eta_{3}-\eta_{4}, \tau_{3}\right)=u_{3}^{*}\left(x, \tau_{3}, \tau_{1},-\eta_{4}, \eta_{3}-\eta_{4}\right) \quad \text { in } Q^{3 *}, \\
& \widetilde{L}_{2 *}=L_{2 *}-Y_{*}, \quad \widetilde{L}_{2}^{*}=L_{2}^{*}-Y^{*},
\end{aligned}
$$

and taking (1)-(10) on the respective characteristics we obtain:

$$
\begin{align*}
& \left(\partial / \partial t-L_{1 *}\right) u_{1 *}=0 \text { in } \quad Q_{*}^{1}, \quad u_{1 *}\left(x, 0, \eta_{1}\right)=u_{1}^{0}\left(x, \eta_{1}\right), \\
& \left(\partial / \partial \tau_{1}-L_{1}^{*}\right) u_{1}^{*}=0 \quad \text { in } Q^{1 *}, \quad u_{1}^{*}\left(x, 0,-\eta_{1}\right)=u_{1}\left(x,-\eta_{1}, 0\right), \\
& \left(\partial / \partial t-\widetilde{L}_{2 *}\right) u_{2 *}=X_{*} \quad \text { in } \bigcup_{k=0}^{4} Q_{k *}^{2}, \quad u_{2 *}\left(x, 0, \eta_{2}\right)=u_{2}^{0}\left(x, \eta_{2}\right), \\
& \left(\partial / \partial \tau_{2}-\widetilde{L}_{2}^{*}\right) u_{2}^{*}=X^{*} \text { in } Q_{k}^{2 *},  \tag{15}\\
& u_{2}^{*}\left(x, \tau_{2}^{k},-\eta_{2}\right)=u_{2}\left(x, \tau_{2}^{k}-\eta_{2}, \tau_{2}^{k}\right), \quad k=\overline{0,4}, \\
& \left(\partial / \partial t-L_{3 *}\right) u_{3 *}=0 \quad \text { in } Q_{*}^{3}, \\
& u_{3 *}\left(x, 0, \tau_{1}, \eta_{3}, \eta_{4}\right)=u_{3}^{0}\left(x, \tau_{1}, \eta_{3}, \eta_{4}\right), \\
& \left(\partial / \partial \tau_{3}-L_{3}^{*}\right) u_{3}^{*}=0 \quad \text { in } Q^{3 *}, \\
& u_{3}^{*}\left(x, 0, \tau_{1},-\eta_{4}, \eta_{3}-\eta_{4}\right)=u_{3}\left(x,-\eta_{4}, \tau_{1}, \eta_{3}-\eta_{4}, 0\right) .
\end{align*}
$$

By virtue of $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{5}\right)$, operators $L_{k *}, L_{k}^{*}, k=1,2,3$ and initial distributions $u_{1 *}\left(x, 0, \eta_{1}\right), u_{2 *}\left(x, 0, \eta_{2}\right), u_{3 *}\left(x, 0, \tau_{1}, \eta_{3}, \eta_{4}\right)$ satisfy all the conditions of Remark 1. If $Y_{*}, Y^{*}, u_{1}\left(x,-\eta_{1}, 0\right), u_{2}\left(x, \tau_{2}^{k}-\eta_{2}, \tau_{2}^{k}\right), u_{3}\left(x,-\eta_{4}, \tau_{1}, \eta_{3}-\eta_{4}, 0\right)$, and $X_{*}, X^{*}$ are known and satisfy all the conditions of Remark 1, then system (15) degenerates into separate problems for $u_{1 *}, u_{1}^{*}, u_{2 *}, u_{2}^{*}, u_{3 *}, u_{3}^{*}$, respectively, of type (11).

Denoting by

$$
\Gamma_{*}^{1}\left(x, t ; y, \xi ; \eta_{1}\right), \quad \Gamma^{1 *}\left(x, \tau_{1} ; y, \xi ;-\eta_{1}\right)
$$

$$
\begin{aligned}
& \Gamma_{k *}^{2}\left(x, t ; y, \xi ; \eta_{2}\right), \quad \Gamma_{k}^{2 *}\left(x, \tau_{2} ; y, \xi ;-\eta_{2}\right), \\
& \Gamma_{*}^{3}\left(x, t ; y, \xi ; \tau_{1}, \eta_{3}, \eta_{4}\right), \quad \Gamma^{3 *}\left(x, \tau_{3} ; y, \xi ; \tau_{1},-\eta_{4}, \eta_{3}-\eta_{4}\right)
\end{aligned}
$$

the fundamental solutions of operators

$$
\begin{array}{ll}
\partial / \partial t-L_{1 *}, & \partial / \partial \tau_{1}-L_{1}^{*}, \\
\partial / \partial t-L_{3 *}, & \partial / \partial \tau_{3}-L_{3}^{*}
\end{array}
$$

in $Q_{*}^{1}, Q^{1 *}, Q_{k *}^{2}, Q_{k}^{2 *}, Q_{*}^{3}, Q^{3 *}$, respectively, from (15), applying general formula (12) to $u_{k *}, u_{k}^{*}, k=1,2,3$, we obtain the system

$$
\begin{aligned}
& u_{1 *}\left(x, t, \eta_{1}\right)= \int_{E^{m}} \Gamma_{*}^{1}\left(x, t ; y, 0 ; \eta_{1}\right) u_{1}^{0}\left(y, \eta_{1}\right) d y \quad \text { in } Q_{*}^{1}, \\
& u_{1}^{*}\left(x, \tau_{1},-\eta_{1}\right)= \int_{E^{m}} \Gamma^{1 *}\left(x, \tau_{1} ; y, 0 ;-\eta_{1}\right) u_{1}\left(y,-\eta_{1}, 0\right) d y \quad \text { in } Q^{1 *}, \\
& u_{2 *}\left(x, t, \eta_{2}\right)= \int_{E^{m}} \Gamma_{k *}^{2}\left(x, t ; y, 0 ; \eta_{2}\right) u_{2}^{0}\left(y, \eta_{2}\right) d y \\
&+\int_{0}^{t} d \xi \int_{E^{m}} \Gamma_{k *}^{2}\left(x, t ; y, \xi ; \eta_{2}\right) X_{*}\left(y, \xi, \eta_{2}\right) d y \quad \text { in } Q_{k *}^{2}, \\
& u_{2}^{*}\left(x, \tau_{2},-\eta_{2}\right)= \int_{E^{m}} \Gamma_{k}^{2 *}\left(x, \tau_{2} ; y, \tau_{2}^{k} ;-\eta_{2}\right) u_{2}\left(y, \tau_{2}^{k}-\eta_{2}, \tau_{2}^{k}\right) d y \\
&+\int_{\tau_{2}^{k}}^{\tau_{2}} d \xi \int_{E^{m}} \Gamma_{k}^{2 *}\left(x, \tau_{2} ; y, \xi ;-\eta_{2}\right) X^{*}\left(y, \xi,-\eta_{2}\right) d y \quad \text { in } Q_{k}^{2 *}, \\
& u_{3 *}\left(x, t, \tau_{1}, \eta_{3}, \eta_{4}\right)=\int_{E^{m}} \Gamma_{*}^{3}\left(x, t ; y, 0 ; \tau_{1}, \eta_{3}, \eta_{4}\right) u_{3}^{0}\left(y, \tau_{1}, \eta_{3}, \eta_{4}\right) d y \quad \text { in } Q_{*}^{3}, \\
& u_{3}^{*}\left(x, \tau_{3}, \tau_{1},-\eta_{4}, \eta_{3}-\eta_{4}\right) \\
&= \int_{E^{m}} \Gamma^{3 *}\left(x, \tau_{3} ; y, 0 ; \tau_{1},-\eta_{4}, \eta_{3}-\eta_{4}\right) u_{3}\left(y,-\eta_{4}, \tau_{1}, \eta_{3}-\eta_{4}, 0\right) d y \quad \text { in } Q^{3 *},
\end{aligned}
$$

which by (4), (6)-(8) can be written as follows

$$
\begin{align*}
& u_{1}\left(x, t, \tau_{1}\right)= \int_{E^{m}} \Gamma_{*}^{1}\left(x, t ; y, 0 ; \tau_{1}-t\right) u_{1}^{0}\left(y, \tau_{1}-t\right) d y \quad \text { in } Q_{*}^{1},  \tag{16}\\
& u_{1}\left(x, t, \tau_{1}\right)= \int_{E^{m}} \Gamma^{1 *}\left(x, \tau_{1} ; y, 0 ; t-\tau_{1}\right) u_{1}\left(y, t-\tau_{1}, 0\right) d y \quad \text { in } Q^{1 *},  \tag{17}\\
& u_{2}\left(x, t, \tau_{2}\right)=\int_{E^{m}} \Gamma_{k *}^{2}\left(x, t ; y, 0 ; \tau_{2}-t\right) u_{2}^{0}\left(y, \tau_{2}-t\right) d y \quad \text { in } Q_{k *}^{2}, \\
& k=0,1,4, \tag{18}
\end{align*}
$$

$$
\begin{gather*}
u_{2}\left(x, t, \tau_{2}\right)=\int_{E^{m}} \Gamma_{k *}^{2}\left(x, t ; y, 0 ; \tau_{2}-t\right) u_{2}^{0}\left(y, \tau_{2}-t\right) d y \\
+\int_{0}^{t} d \xi \int_{E^{m}} d y \Gamma_{k *}^{2}\left(x, t ; y, \xi ; \tau_{2}-t\right) \int_{\sigma_{1}} u_{3}\left(y, \xi, \tau_{1}, \xi+\tau_{2}-t, T\right) d \tau_{1}  \tag{19}\\
\quad \operatorname{in~} Q_{k *}^{2}, \quad k=2,3
\end{gather*}
$$

$$
\begin{equation*}
u_{2}\left(x, t, \tau_{2}\right)=\int_{E^{m}} \Gamma_{k}^{2 *}\left(x, \tau_{2} ; y, \tau_{2}^{k} ; t-\tau_{2}\right) u_{2}\left(y, \tau_{2}^{k}+t-\tau_{2}, \tau_{2}^{k}\right) d y \tag{20}
\end{equation*}
$$

$$
\text { in } Q_{k}^{2 *}, \quad k=0,1,4
$$

$$
u_{2}\left(x, t, \tau_{2}\right)=\int_{E^{m}} \Gamma_{k}^{2 *}\left(x, \tau_{2} ; y, \tau_{2}^{k} ; t-\tau_{2}\right) u_{2}\left(y, \tau_{2}^{k}+t-\tau_{2}, \tau_{2}^{k}\right) d y
$$

$$
+\int_{\tau_{2}^{k}}^{\tau_{2}} d \xi \int_{E^{m}} d y \Gamma_{k}^{2 *}\left(x, \tau_{2} ; y, \xi ; t-\tau_{2}\right)
$$

$$
\begin{equation*}
\times \int_{\sigma_{1}} u_{3}\left(y, \xi+t-\tau_{2}, \tau_{1}, \xi, T\right) d \tau_{1} \quad \text { in } Q_{k}^{2 *}, \quad k=2,3 \tag{21}
\end{equation*}
$$

$$
u_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right)=\int_{E^{m}} \Gamma_{*}^{3}\left(x, t ; y, 0 ; \tau_{1}, \tau_{2}-t, \tau_{3}-t\right)
$$

$$
\begin{equation*}
\times u_{3}^{0}\left(y, \tau_{1}, \tau_{2}-t, \tau_{3}-t\right) d y \quad \text { in } Q_{*}^{3} \tag{22}
\end{equation*}
$$

$$
u_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right)=\int_{E^{m}} \Gamma^{3 *}\left(x, \tau_{3} ; y, 0 ; \tau_{1}, t-\tau_{3}, \tau_{2}-\tau_{3}\right)
$$

$$
\begin{equation*}
\times u_{3}\left(y, t-\tau_{3}, \tau_{1}, \tau_{2}-\tau_{3}, 0\right) d y \quad \text { in } Q^{3 *} \tag{23}
\end{equation*}
$$

$$
u_{3}\left(x, t, \tau_{1}, \tau_{2}, 0\right)=p\left(x, t, \tau_{1}, \tau_{2}\right) u_{1}\left(x, t, \tau_{1}\right) u_{2}\left(x, t, \tau_{2}\right) / n_{1}(x, t)
$$

$$
\begin{equation*}
n_{1}=\int_{\sigma_{1}} u_{1} d \tau_{1} \tag{24}
\end{equation*}
$$

$$
\begin{equation*}
u_{1}(x, t, 0)=\int_{\sigma} b_{1} u_{3}\left(x, t, \tau_{1}, \tau_{2}, T\right) d \sigma \tag{25}
\end{equation*}
$$

$$
\begin{equation*}
u_{2}(x, t, 0)=\int_{\sigma} b_{2} u_{3}\left(x, t, \tau_{1}, \tau_{2}, T\right) d \sigma \tag{26}
\end{equation*}
$$

We must add to (20) and (21) the continuity condition $\left[\left.u\right|_{\tau_{2}=\tau_{2}^{k}}\right]=0, k=\overline{1.4}$.
Now we will prove that (16)-(26) represent the solution of (1)-(10). Consider system (16)-(26) going along the axis $t$ by step $T$. Since $L_{1 *}, L_{2 *}$ in $Q_{0 *}^{2} \cup Q_{4 *}^{2}$ and $L_{3 *}$ satisfy the conditions of Remark 1, functions (16), (18) for $k=0$ and (22) express positive $u_{1}$, $u_{2}$ and $u_{3}$ in $Q_{*}^{1}, Q_{0 *}^{2} \cup Q_{4 *}^{2}$ and $Q_{*}^{3}$, respectively. Hence, by virtue of $\left(\mathrm{H}_{1}\right)$ we observe that $\left.n_{1}\right|_{\text {suppa } p\left(\cdot, t, \tau_{1}, \tau_{2}\right)} \geqslant \widetilde{n}_{1}$ and

$$
p\left(x, t, \tau_{1}, \tau_{2}\right) u_{1}\left(x, t, \tau_{1}\right) / n_{1}(x, t) \in C^{0}\left(E^{m} \times\left[0, \tau_{11}\right] \times \bar{\sigma}_{1} \times \bar{\sigma}_{2}(0)\right)
$$

where $\widetilde{n}_{1}$ is a positive constant, while from (22) by (13) it follows that

$$
\begin{equation*}
\left|u_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right)-u_{3}\left(y, t, \tau_{1}, \tau_{2}, \tau_{3}\right)\right| \leqslant \kappa_{1}|x-y| t^{-1 / 2} \quad \text { in } Q_{*}^{3} \tag{27}
\end{equation*}
$$

with $\kappa_{1}$ a constant.
Let $t \in[0, T]$ and assume $\omega_{1}=E^{m} \times[0, T] \times \bar{I}$. By means of (25), (26), $\left(H_{2}\right)$ and due to the continuity of $u_{3}$ (see Remark 1) we obtain continuos $u_{1}(x, t, 0)$ and $u_{2}(x, t, 0) \forall(x, t) \in E^{m} \times[0, T]$. Now from (17) and (20) for $k=0$ we get continuos $u_{1}$ and $u_{2}$ in $Q^{1 *} \cap \omega_{1}$ and $Q_{0}^{2 *} \cap \omega_{1}$, respectively. Then by $\left(\mathrm{H}_{1}\right)$ it follows that

$$
\begin{aligned}
& Y\left(x, t, \tau_{2}\right) \in C^{0}\left(E^{m} \times[0, T] \times \bar{\sigma}_{2}(0)\right), \\
& \left|Y\left(x, t, \tau_{2}\right)-Y\left(y, t, \tau_{2}\right)\right|=\left|\int_{0}^{1}(x-y) \cdot \nabla_{z} Y\left(z, t, \tau_{2}\right)\right|{ }_{z=y+\gamma(x-y)} d \gamma \mid \\
& \leqslant|x-y| \sup _{E^{m} \times(0, T] \times \sigma_{2}(0)}\left|\nabla_{x} Y\left(x, t, \tau_{2}\right)\right|,
\end{aligned}
$$

where $\nabla_{x}$ and $(x-y) \cdot \nabla_{z}$ mean the gradient operator and scalar product, respectively. Since

$$
\left|\nabla_{x} Y\left(x, t, \tau_{2}\right)\right| \leqslant n_{1}^{-1}\left|\int_{\sigma_{1}}\left(u_{1} \nabla_{x} p+p \nabla_{x} u_{1}\right) d \tau_{1}\right|+n_{1}^{-2}\left|\nabla_{x} n_{1}\right| \int_{\sigma_{1}} p u_{1} d \tau_{1},
$$

we have:

$$
n_{1}^{-1}\left|\int_{\sigma_{1}} u_{1} \nabla_{x} p d \tau_{1}\right| \leqslant \kappa_{2}
$$

by $\left(\mathrm{H}_{1}\right)$ and because

$$
\left.n_{1}\right|_{\text {suppa } p\left(\cdot, t, \tau_{1}, \tau_{2}\right)} \geqslant \widetilde{n}_{2}
$$

and

$$
n_{1}^{-1} \int_{\sigma_{1}} p\left|\nabla_{x} u_{1}\right| d \tau_{1}+n_{1}^{-2}\left|\nabla_{x} n_{1}\right| \int_{\sigma_{1}} p u_{1} d \tau_{1} \leqslant \kappa_{3} \int_{\sigma_{1}} p t^{-1 / 2} d \tau_{1} \leqslant \kappa_{2}
$$

by $\left(\mathrm{H}_{1}\right)$ and boundedness of $u_{1}$ and because of the estimates

$$
\begin{aligned}
& \left.n_{1}\right|_{\operatorname{suppa} p\left(\cdot, t, \tau_{1}, \tau_{2}\right)} \geqslant \widetilde{n}_{2}, \\
& \left.\left|\nabla_{x} u_{1}\right|\right|_{\tau_{1} \in \sigma_{1}} \leqslant \kappa_{4}\left\{\begin{array}{ll}
t^{-1 / 2}, & t \leqslant \tau_{1} \\
1, & t \in\left(\tau_{1}, T\right]
\end{array}\right\} \leqslant \kappa_{4} t^{-1 / 2} \quad \text { for } t \in(0, T]
\end{aligned}
$$

where $\kappa_{2}, \kappa_{3}, \kappa_{4}$ and $\widetilde{n}_{2}$ are some positive constants. The estimate for $\left|\nabla_{x} u_{1}\right|$ follows from (16), (17) and is based on the estimates (see Garoni and Menaldi, 1992; Ladyzhen-
skaya et al., 1967)

$$
\begin{aligned}
& \left|\nabla_{x} \Gamma^{1 *}\left(x, \tau_{1} ; y, 0 ;-\eta\right)\right| \leqslant c \tau_{1}^{-(m+1) / 2} \exp \left\{-C|x-y| / \tau_{1}\right\} \\
& \left|\nabla_{x} \Gamma_{*}^{1}\left(x, t ; y, 0 ; \eta_{1}\right)\right| \leqslant c t^{-(m+1) / 2} \exp \{-C|x-y| / t\}
\end{aligned}
$$

$c$ and $C$ being some positive constants.
Thus $\left|Y\left(x, t, \tau_{2}\right)-Y\left(y, t, \tau_{2}\right)\right| \leqslant \kappa|x-y|$ with $\kappa$ a constant. Hence $Y\left(x, t, \tau_{2}\right)$ is Lipshitz continuous with respect to $x$ in $E^{m} \times[0, T] \times \bar{\sigma}_{2}(0)$ (i.e., $Y \in C\left(E^{m} \times\right.$ $\left.[0, T] \times \bar{\sigma}_{2}(0)\right)$, and $\left(\mathrm{H}_{4}\right)$ shows that $\widetilde{L}_{2 *}$ and $\widetilde{L}_{2}^{*}$ satisfy all the conditions of Remark 1 in $\left(Q_{1 *}^{2} \cup Q_{2 *}^{2}\right) \cap \omega_{1}$ and $\left(Q_{1}^{2 *} \cup Q_{2}^{2 *}\right) \cap \omega_{1}$, respectively. Therefore we can construct $\Gamma_{1 *}^{2}, \Gamma_{2 *}^{2}, \Gamma_{1}^{2 *}, \Gamma_{2}^{2 *}$. Then (18) and (20) for $k=1$ yield $u_{2}$ in $\left(Q_{1 *}^{2} \cup Q_{1}^{2 *}\right) \cap \omega_{1}$, while from (19) and (21) by (22), (27) we get $u_{2}$ in $\left(Q_{2 *}^{2} \cup Q_{3 *}^{2}\right) \cap \omega_{1}$ and $\left(Q_{2}^{2 *} \cup Q_{3}^{2 *}\right) \cap \omega_{1}$, respectively. Eq. (20) for $k=4$ gives $u_{2}$ in $Q_{4}^{2 *} \cap \omega_{1}$.

Let $t \in(T, 2 T]$ and assume $\omega_{2}=E^{m} \times[T, 2 T] \times \bar{I}$. Knowing $u_{1}$ and $u_{2}$ for $t \in[0, T]$ by (24), $\left(\mathrm{H}_{1}\right)$ and because $\left.n_{1}\right|_{\text {suppa } p\left(\cdot, t, \tau_{1}, \tau_{2}\right)} \geqslant \widetilde{n}_{1}$ we get continuous $u_{3}\left(x, t, \tau_{1}, \tau_{2}, 0\right)$ for $t \in\left(\tau_{3}, T\right]$, then by (23) obtain $u_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right)$ for $t \in\left(\tau_{3}, \tau_{3}+T\right]$. Observe that, by Remark 1, $\left|\nabla_{x} u_{3}\right|_{\tau_{3}=T} \mid$ for $t>T$ is bounded. From (25), (26), by using ( $\mathrm{H}_{2}$ ) and known continuous $\left.u_{3}\right|_{\tau_{3}=T}$ we get continuous $\left.u_{1}\right|_{\tau_{1}=0}$ and $\left.u_{2}\right|_{\tau_{2}=0}$ too. Then by virtue of (17) with known $\left.u_{1}\right|_{\tau_{1}=0}$ and (20) with known $\left.u_{2}\right|_{\tau_{2}=0}$ we obtain $u_{1}$ and $u_{2}$ in $Q^{1 *} \cap \omega_{2}, Q_{0}^{2 *} \cap \omega_{2}$, respectively. Now we can construct $Y^{*}, Y_{*}$ and, by the same arguments as before, prove that $\widetilde{L}_{2}^{*}$ and $\widetilde{L}_{2 *}$ satisfy the conditions of Remark 1 . Thus we can obtain $\Gamma_{1}^{2 *}, \Gamma_{2}^{2 *}$ and $\Gamma_{2 *}^{2}\left(\right.$ if $\left.\tau_{22}-\tau_{21}>2 T\right)$, which allows us by (20) for $k=1$, (21) for $k=2$, (19) for $k=2$, (21) for $k=3$, (20) for $k=4$, and (18) for $k=4$ to construct $u_{2}$ in $\left(\bigcup_{s=1}^{4} Q_{k}^{2 *} \cup Q_{2 *}^{2}\right) \cap \omega_{2}$.

Proceeding our reasoning we obtain $u_{1}, u_{2}$ and $u_{3}$ for $t \in\left[2 T, t^{*}\right]$. Restrictions (10) ensure the continuity of $u_{1}, u_{2}, u_{3}$ across the lines $t=\tau_{1}, t=\tau_{2}, t=\tau_{3}$, respectively. So Theorem 1 is proved.

Corollary 2. Under the hypotheses $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{5}\right)$ for $k=1,2$, there exists continuous $u_{1}$ and $u_{2}$ satisfying problem (1)-(10) in $Q_{*}^{1}$ and $Q_{4 *}^{2}$, respectively. If $\overline{\bar{Q}}_{k} \nu_{k}>0$ and $u_{k}^{0}\left(x, \tau_{k}\right) \rightarrow 0$ as $\tau_{k} \rightarrow \infty, k=1,2$, then so does $u_{k}\left(x, t, \tau_{k}\right)$ for $t \leqslant \min \left(\tau_{1}, \tau_{2}\right)$, $x \in E^{m}$.

The proof of Corollary follows from the maximum principle (see Friedman, 1968; Garoni and Menaldi, 1992; Ladyzhenskaya et al., 1967).

## 7. Population Growth and Decay

In this section we consider the case where dispersal moduli $a_{i j}^{3}$ and $a_{i}^{3}, i, j=\overline{1, m}$ are not depending on age $\tau_{1}$ of the mated male, and prove Theorem 2 and Theorem 3.

## Proof of Theorem 2

Set $\widetilde{L}_{3}\left(x, t, \tau_{2}, \tau_{3}\right)=\sum_{i, j=1}^{m} a_{i j}^{3} \partial^{2} / \partial x_{i} \partial x_{j}+\sum_{i=1}^{m} a_{i}^{3} \partial / \partial x_{i}$.
Let $\widetilde{\Gamma}_{3 *}\left(x, t ; y, \xi ; \eta_{3}, \eta_{4}\right)\left(\right.$ resp. $\left.\widetilde{\Gamma}_{3}^{*}\left(x, \tau_{3} ; y, \xi ;-\eta_{4}, \eta_{3}-\eta_{4}\right)\right)$ be the fundamental solution of operator $\partial / \partial t-\widetilde{L}_{3 *}$ in $Q_{*}^{3}\left(\right.$ resp. $\partial / \partial \tau_{3}-\widetilde{L}_{3 *}$ in $\left.Q^{3 *}\right)$. Then classic solution of the problem

$$
\begin{aligned}
& \left(\partial / \partial t-\widetilde{L}_{3}\right) \widetilde{u}_{3}=0 \quad \text { in } Q_{3} \\
& \left.\widetilde{u}_{3}\right|_{t=0}=u_{3}^{0} \quad \text { in } E^{m} \times \sigma_{1} \times \sigma_{2}\left(\tau_{3}\right) \times \sigma_{3}, \\
& \left.\widetilde{u}_{3}\right|_{\tau_{3}=0}=u_{3}\left(x, t, \tau_{1}, \tau_{2}, 0\right) \quad \text { in } E^{m} \times I \times \sigma_{1} \times \sigma_{2}(0)
\end{aligned}
$$

with given suitable $u_{3}^{0}$ and $u_{3}\left(x, t, \tau_{1}, \tau_{2}, 0\right)=p u_{1} u_{2} / n_{1}$ reads

$$
\widetilde{u}_{3}\left(x, t, \tau_{1}, \tau_{2}, \tau_{3}\right)=\left\{\begin{aligned}
\int_{E^{m}} & \widetilde{\Gamma}_{*}^{3}\left(x, t ; y, 0 ; \tau_{2}-t, \tau_{3}-t\right) \\
& \times u_{3}^{0}\left(y, \tau_{1}, \tau_{2}-t, \tau_{3}-t\right) d y \quad \text { in } Q_{*}^{3} \\
\int_{E^{m}} & \widetilde{\Gamma}^{3 *}\left(x, \tau_{3} ; y, 0 ; t-\tau_{3}, \tau_{2}-\tau_{3}\right) \\
& \times u_{3}\left(y, t-\tau_{3}, \tau_{1}, \tau_{2}-\tau_{3}, 0\right) d y \quad \text { in } Q^{3 *}
\end{aligned}\right.
$$

and by Lemma 2 verifies $u_{3} \leqslant \widetilde{u}_{3}$ in $Q_{3}$. Hence by (22)-(24),

$$
\begin{aligned}
& \int_{\sigma_{1}} u_{3} d \tau_{1} \leqslant \int_{E^{m}} d y \widetilde{\Gamma}_{*}^{3}\left(x, t ; y, 0 ; \tau_{2}-t, \tau_{3}-t\right) \int_{\sigma_{1}} u_{3}^{0}\left(y, \tau_{1}, \tau_{2}-t, \tau_{3}-t\right) d \tau_{1} \\
& \quad \text { in } Q_{*}^{3} \\
& \int_{\sigma_{1}} u_{3} d \tau_{1} \leqslant \int_{E^{m}} d y \widetilde{\Gamma}^{3 *}\left(x, \tau_{3} ; y, 0 ; t-\tau_{3}, \tau_{2}-\tau_{3}\right) \\
& \times\left.\int_{\sigma_{1}}\left(p u_{1} u_{2} / n_{1}\right)\right|_{\left(y, t-\tau_{3}, \tau_{1}, \tau_{2}-\tau_{3}\right)} d \tau_{1} \quad \text { in } Q^{3 *}
\end{aligned}
$$

and since

$$
\begin{aligned}
& \int_{E^{m}} \widetilde{\Gamma}_{*}^{3}\left(x, t ; y, \xi ; \tau_{2}-t, \tau_{3}-t\right) d y \leqslant 1 \\
& \int_{E^{m}} \widetilde{\Gamma}^{3 *}\left(x, \tau_{3} ; y, \xi ; t-\tau_{3}, \tau_{2}-\tau_{3}\right) d y \leqslant 1
\end{aligned}
$$

we have

$$
\int_{\sigma_{1}} u_{3} d \tau_{1} \leqslant\left\{\begin{array}{l}
\widehat{u}_{3} \quad \text { in } Q_{*}^{3}  \tag{28}\\
\widehat{p} \sup _{y \in E^{m}} u_{2}\left(y, t-\tau_{3}, \tau_{2}-\tau_{3}\right) \quad \text { in } \quad Q_{*}^{3} \text { for } t-\tau_{3} \in \bar{I}^{*}
\end{array}\right.
$$

So assertion (i) is proved.
It remains to prove assertion (ii). We establish inequality (ii) going along the axis $t$ by the step $T$.

Let $t \in[0, T]$. From (25), (26), by (28) $)_{1}$ with $\tau_{3}=T$ we conclude that

$$
\begin{equation*}
\left.u_{k}\right|_{\tau_{k}=0} \leqslant \widehat{b} \widehat{u}_{3} \leqslant \delta \widehat{u}, \quad k=1,2 \quad \text { in } E^{m} \times[0, T] \tag{29}
\end{equation*}
$$

then from (16)-(21), by (28), (29) and the maximum principle that

$$
\begin{equation*}
u_{2} \leqslant \delta \widehat{u} \quad \text { for } \quad\left(x, t, \tau_{2}\right) \in E^{m} \times[0, T] \times \bar{I}, \tag{30}
\end{equation*}
$$

and finally that

$$
\begin{equation*}
\int_{\sigma} u_{3} \leqslant \widehat{p} \delta \widehat{u} \quad \text { for } x \in E^{m}, t \in\left(\tau_{3}, \tau_{3}+T\right], \tau_{2} \in \sigma_{2}\left(\tau_{3}\right), \tau_{3} \in \sigma_{3} . \tag{31}
\end{equation*}
$$

Let $t \in(T, 2 T]$. Estimate (31) with $\tau_{3}=T$ and (25), (26) yield

$$
\begin{equation*}
\left.u_{k}\right|_{\tau_{k}=0} \leqslant \widehat{b} \widehat{p} \delta \widehat{u} \leqslant \gamma \delta \widehat{u}, \quad k=1,2 \quad \text { in } E^{m} \times(T, 2 T] . \tag{32}
\end{equation*}
$$

Then from (18)-(21) by using (32), (31) and the maximum principle we get

$$
\begin{equation*}
u_{2} \leqslant \gamma \delta \widehat{u} \quad \text { in } E^{m} \times(T, 2 T] \times \bar{I}, \tag{33}
\end{equation*}
$$

which together with (28) yields,

$$
\begin{equation*}
\int_{\sigma_{1}} u_{3} d \tau_{1} \leqslant \widehat{p} \gamma \delta \widehat{u} \quad \text { in } E^{m} \times\left(\tau_{3}, \tau_{3}+2 T\right] \times \sigma_{2}\left(\tau_{3}\right) \times \sigma_{3} \tag{34}
\end{equation*}
$$

Proceeding our argument we prove (ii) for $u_{2}$, while this one for $u_{1}$ follows from the maximum principle. More rough estimate $u_{k} \leqslant \delta \widehat{u} \gamma^{t / T} \quad$ in $\bar{Q}_{k}, k=1,2$ immediately follows. So Theorem 2 is proved.

## Proof of Theorem 3

We consider the case $\tau_{21}>T$. One can analyze the opposite case in the similar way. The assertion (i) is the same as that in Theorem 2. Therefore we have to prove the statement (ii).

Let $t \in[0, T]$. As in the proof of Theorem 2, we obtain

$$
\begin{aligned}
& \left.\int_{\sigma_{1}} u_{3}\right|_{\tau_{3}=T} d \tau_{1} \leqslant \widehat{u}_{3} \quad \text { in } E^{m} \times[0, T] \times \sigma_{2}(T) \\
& \left.u_{k}\right|_{\tau_{k}=0} \leqslant \widehat{b} \widehat{u}_{3}=q \widehat{u} \quad \text { for } t \in[0, T]
\end{aligned}
$$

$$
\begin{align*}
u_{2} & \leqslant q \widehat{u} \quad \text { in } E^{m} \times[0, T] \times[0, t), \\
u_{2} & \leqslant \widehat{u} \max \left(1, \widehat{u}_{3} /(\widehat{\nu} \widehat{u})\right) \\
& \leqslant \widehat{u} \max (1, q /(\widehat{b} \widehat{\nu})) \leqslant \widehat{u} \quad \text { in } E^{m} \times[0, T] \times[t, \infty) . \tag{35}
\end{align*}
$$

Let $t \in(T, 2 T]$. From (i) and (35) it follows that

$$
\begin{equation*}
\left.\int_{\sigma_{1}} u_{3}\right|_{\tau_{3}=T} d \tau_{1} \leqslant \widehat{p} \widehat{u} \quad \text { in } E^{m} \times(T, 2 T] \times \sigma_{2}(T) \tag{36}
\end{equation*}
$$

which together with (25) and (26) gives

$$
\left.u_{k}\right|_{\tau_{k}=0} \leqslant \widehat{b} \widehat{p} \widehat{u} \leqslant q \widehat{u} \quad \text { for } \quad t \in(T, 2 T] .
$$

Hence, by (18)-(21), (36) and because of $\tau_{2}^{2}>2 T$,

$$
\begin{aligned}
& u_{2} \leqslant q \widehat{u} \quad \text { in } E^{m} \times(T, 2 T] \times[0, t), \\
& u_{2} \leqslant \max (\widehat{u}, \widehat{u} \widehat{p} / \widetilde{\nu}) \leqslant \widehat{u} \max (1, q / \widehat{b} \widehat{\nu}) \leqslant \widehat{u} \quad \text { in } E^{m} \times(T, 2 T] \times[t, \infty) .
\end{aligned}
$$

In a similar way we obtain

$$
\begin{align*}
& \left.\int_{\sigma_{1}} u_{3}\right|_{\tau_{3}=T} d \tau_{1} \leqslant \widehat{p} \widehat{u} \quad \text { in } E^{m} \times\left[0, \tau_{2}^{2}\right] \times \sigma_{2}(T),  \tag{37}\\
& u_{2} \leqslant \widehat{u} \begin{cases}q & \text { in } E^{m} \times\left[0, \tau_{2}^{2}\right] \times[0, t), \\
1 & \text { in } E^{m} \times\left[0, \tau_{2}^{2}\right] \times[t, \infty)\end{cases} \tag{38}
\end{align*}
$$

Let $t \in\left(\tau_{2}^{2}, \tau_{2}^{4}\right]$. From (25), (26), by (i), one can write

$$
\left.u_{k}\right|_{\tau_{k}=0} \leqslant \widehat{p} \int_{\sigma_{2}(T)} \sup _{\tau_{1} \in \sigma_{1}} b_{k} \sup _{y \in E^{m}} u_{2}\left(y, t-T, \tau_{2}-T\right) d \tau_{2}
$$

and taking into account (38) get

$$
\left.u_{k}\right|_{\tau_{k}=0} \leqslant \widehat{p}\left(q \widehat{u} \int_{\tau_{2}^{2}}^{t} \sup _{\tau_{1} \in \sigma_{1}} b_{k} d \tau_{2}+\widehat{u} \int_{t}^{\tau_{2}^{4}} \sup _{\tau_{1} \in \sigma_{1}} b_{k} d \tau_{2}\right) .
$$

Hence

$$
\begin{equation*}
\left.\left.u_{k}\right|_{\tau_{k}=0} \leqslant \widehat{p} \widehat{u} \widehat{b} \leqslant q \widehat{u} \quad \text { in } E^{m} \times\left(\tau_{2}^{2}, \tau_{2}^{4}\right], \quad k=1,2 .\right) \tag{39}
\end{equation*}
$$

From (20), by (38), (39), it follows that

$$
\begin{equation*}
u_{2} \leqslant q \widehat{u} \quad \text { in } E^{m} \times\left(\tau_{2}^{2}, \tau_{2}^{4}\right] \times\left[0, \tau_{2}^{2}\right] . \tag{40}
\end{equation*}
$$

Eqs. (19) (in the case $\tau_{2}^{3}>2 \tau_{2}^{2}$ ) and (21), estimates (i) with $\tau_{3}=T$, (38), (40), and the maximum principle show that

$$
u_{2} \leqslant \widehat{u} \begin{cases}q & \text { in } E^{m} \times\left(\tau_{2}^{2}, \tau_{2}^{4}\right] \times[0, t) \\ 1 & \text { in } E^{m} \times\left(\tau_{2}^{2}, \tau_{2}^{4}\right] \times[t, \infty)\end{cases}
$$

Let $t \in\left(\tau_{2}^{4}, 2 \tau_{2}^{4}\right]$. Reasoning as above we obtain

$$
\left.u_{k}\right|_{\tau_{k}=0} \leqslant \widehat{p} \widehat{b} q \widehat{u} \leqslant q^{2} \widehat{u} \quad \text { in } E^{m} \times\left(\tau_{2}^{4}, 2 \tau_{2}^{4}\right],
$$

and

$$
u_{2} \leqslant \widehat{u} \begin{cases}q^{2} & \text { in } E^{m} \times\left(\tau_{2}^{4}, 2 \tau_{2}^{4}\right] \times\left[0, t-\tau_{2}^{4}\right), \\ q & \text { in } E^{m} \times\left(\tau_{2}^{4}, 2 \tau_{2}^{4}\right] \times\left[t-\tau_{2}^{4}, t\right), \\ 1 & \text { in } E^{m} \times\left(\tau_{2}^{4}, 2 \tau_{2}^{4}\right] \times[t, \infty) .\end{cases}
$$

Continuing our argument we prove the assertion (ii) for $u_{2}$, then, from (16), (17) and the maximum principle, statement (ii) follows for $u_{1}$. This ends the proof.

## 8. One More Estimate for $u_{1}$ and $u_{2}$ Growth.

In this section we obtain upper estimates for $u_{1}, u_{2}$ and $\int_{\sigma_{1}} u_{3} d \tau_{1}$ based on the population intrinsic growth rate $\lambda_{0}$. Under the hypotheses of Theorem 2 by the comparison principle we can prove that $u_{1}, u_{2}$ and $\int_{\sigma_{1}} u_{3} d \tau_{1}$ possess majorants $U\left(t, \tau_{1}\right), U\left(t, \tau_{2}\right)$ and $U_{3}\left(t, \tau_{2}, \tau_{3}\right)$, respectively, satisfying the following problem

$$
\begin{aligned}
& \left(D_{1}-\nu_{1 *}\right) U_{1}=0 \quad \text { in } I \times I, \\
& \left(D_{2}-\nu_{2 *}\right) U_{2}=-U_{2} \begin{cases}0, & \tau_{2} \notin \sigma_{2}(0), \\
p_{*}, & \tau_{2} \in \sigma_{2}(0)\end{cases} \\
& \quad+ \begin{cases}0, & \tau_{2} \notin \sigma_{2}(T), \quad \text { in } I \times\left(I \backslash \bigcup_{s=1}^{4} \tau_{2}^{s}\right), \\
\left.U_{3}\right|_{\tau_{3}=T}, & \tau_{2} \in \sigma_{2}(T)\end{cases} \\
& \left(D_{3}-\nu_{3 *}\right) U_{3}=0 \quad \text { in } I \times \sigma_{2}\left(\tau_{3}\right) \times \sigma_{3}, \\
& \left.U_{1}\right|_{t=0}=U_{1}^{0},\left.\quad U_{2}\right|_{t=0}=U_{2}^{0},\left.\quad U_{3}\right|_{t=0}=U_{3}^{0}, \\
& \left.U_{1}\right|_{\tau_{1}=0}=\left.\int_{\sigma_{2}(T)} b_{1}^{*} U_{3}\right|_{\tau_{3}=T} d \tau_{2},\left.\quad U_{2}\right|_{\tau_{2}=0}=\left.\int_{\sigma_{2}(T)} b_{2}^{*} U_{3}\right|_{\tau_{3}=T} d \tau_{2}, \\
& \left.U_{3}\right|_{\tau_{3}=0}=p^{*} U_{2}, \quad\left[\left.U_{2}\right|_{\tau_{2}=\tau_{2}^{s}}\right]=0, \quad s=\overline{1,4},
\end{aligned}
$$

where:

$$
\nu_{1 *}\left(\tau_{1}\right)=\inf _{(x, t) \in E^{m} \times \bar{I}} \nu_{1}, \quad \nu_{2 *}\left(\tau_{2}\right)=\inf _{(x, t) \in E^{m} \times \bar{I}} \nu_{2}
$$

$$
\begin{aligned}
& \nu_{3 *}\left(\tau_{2}, \tau_{3}\right)=\inf _{\left(x, t, \tau_{1}\right) \in E^{m} \times \bar{I} \times \bar{\sigma}_{1}} \nu_{3} \\
& U_{1}^{0}\left(\tau_{1}\right)=\sup _{x \in E^{m}} u_{1}^{0}, \quad U_{2}^{0}\left(\tau_{2}\right)=\sup _{x \in E^{m}} u_{2}^{0}, \quad U_{3}^{0}\left(\tau_{2}, \tau_{3}\right)=\sup _{x \in E^{m}} \int_{\sigma_{1}} u_{3}^{0} d \tau_{1}, \\
& b_{1}^{*}\left(\tau_{2}\right)=\sup _{\left(x, t, \tau_{1}\right) \in E^{m} \times \bar{I} \times \bar{\sigma}_{1}} b_{1}, \quad b_{2}^{*}\left(\tau_{2}\right)=\sup _{\left(x, t, \tau_{1}\right) \in E^{m} \times \bar{I} \times \bar{\sigma}_{1}} b_{2} \\
& p_{*}\left(\tau_{2}\right)=\inf _{\left(x, t, \tau_{1}\right) \in E^{m} \times \bar{I} \times \bar{\sigma}_{1}} p, \quad p^{*}\left(\tau_{2}\right)=\sup _{\left(x, t, \tau_{1}\right) \in E^{m} \times \bar{I} \times \bar{\sigma}_{1}} p
\end{aligned}
$$

In (Skakauskas, 1997) we have constructed the following largetime $\left(\max \left(\tau_{1}, \tau_{2}\right)<t\right)$ asymptotic behavior of $U_{1}, U_{2}$ and $U_{3}$ :

$$
\begin{aligned}
U_{1} & \sim c_{1} \exp \left\{\lambda_{0}\left(t-\tau_{1}\right)-\int_{0}^{\tau_{1}} \nu_{1 *}(\eta) d \eta\right\} \\
U_{2} & \sim c_{2} f_{2}\left(\tau_{2}\right) \exp \left\{\lambda_{0}\left(t-\tau_{1}\right)\right\} \\
U_{3} & \sim c_{2} p^{*}\left(\tau_{2}-\tau_{3}\right) f_{2}\left(\tau_{2}-\tau_{3}\right) \exp \left\{\lambda_{0}\left(t-\tau_{2}\right)-\int_{0}^{\tau_{3}} \nu_{3 *}\left(\eta+\tau_{2}-\tau_{3}, \eta\right) d \eta\right\}
\end{aligned}
$$

where $c_{1}, c_{2}$ are two positive constants, $\lambda_{0}$ is a unique real root of the characteristic equation

$$
\int_{\sigma_{2}(0)} b_{2}^{*}(\eta+T) g(\eta) f_{2}(\eta) \exp \{-\lambda \eta\} d \eta=1
$$

and $f_{2}\left(\tau_{2}\right)$ satisfies the following equation

$$
\begin{aligned}
& \left(\frac{d}{d \tau_{2}}-\nu_{2 *}\right) f_{2}=- \begin{cases}0, & \tau_{2} \notin \sigma_{2}(0), \\
p_{*}, & \tau_{2} \in \sigma_{2}(0)\end{cases} \\
& \quad+ \begin{cases}0, & \tau_{2} \notin \sigma_{2}(T), f_{2}(0)=1,\left[f_{2}\left(\tau_{2}^{i}\right)\right]=0, i=1,4, \\
g\left(\tau_{2}\right) f_{2}\left(\tau_{2}-T\right), & \tau_{2} \in \sigma_{2}(T),\left[f_{2}\left(\tau_{2}^{i}\right)\right]=0, i=2,3\end{cases}
\end{aligned}
$$

with $g\left(\tau_{2}\right)=p^{*}\left(\tau_{2}-T\right) \exp \left\{-\int_{0}^{T} \nu_{3 *}\left(\eta+\tau_{2}-T, \eta\right) d \eta\right\}$.
Clearly, $u_{1}, u_{2}$ vanish as $t$ increases and $\lambda_{0}<0$.

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# Vieno migruojančios populiacijos amžiaus ir lyčiu struktūros dinamikos modelio matematinė analizė, iskaitant atsitiktini kryžminimasi ir pateliu nėštuma 

Vladas SKAKAUSKAS
Tiriamas vieno migruojančios populiacijos amžiaus ir lyčiu struktūros dinamikos modelio klasikinis išspendžiamumas. Populiaciją sudaro patineliai, neapvaisintos ir apvaisintos patelès. Reproduktyvieji intervalai ir něštumo trukmè laikomi fiksuotais, o kryžminimosi sistema, nesudarant pastoviuju vedybiniu poru, yra atsitiktinė. Individu migracijos mechanizmas aprašomas bendruoju tiesiniu tolygiai elipsiniu 2 -osios eilès operatoriumi daugiamatèje erdvèje. Irodytas klasikinio sprendinio egzistavimas ir vienatis.

