

# A Reversible Data Hiding Based on Histogram Shifting of Prediction Errors for Two-Tier Medical Images

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**Abstract.** Clinics and hospitals have already adopted more technological resources to provide a faster and more precise diagnostic for patients, health care providers, and institutes of medicine. Security issues get more and more important in medical services via communication resources such as Wireless-Fidelity (Wi-Fi), third generation of mobile telecommunications technology (3G), and other mobile devices to connect medical systems from anywhere. Furthermore, cloud-based medical systems allow users to access archived medical images from anywhere. In order to protect medical images, lossless data hiding methods are efficient and easy techniques. In this paper, we present a data hiding of two-tier medical images based on histogram shifting of prediction errors. The median histogram shifting technique and prediction error schemes as the two-tier hiding have high capacity and PSNR in 16-bit medical images.

**Key words:** lossless data embedding, reversible data hiding, histogram, prediction, medical image.

## 1. Introduction

Mobile and digital media are getting more and more popular on Internet and cloud services. In social networks, many multi-media such as images, videos, and audios are produced by different aspects of the human activities. Moreover, telemedicine applies telecommunication and information technology to offer clinical health care from a distance. In critical care and emergency situations, health informatics, medical, and imaging data are transmitted from doctors and healthcare professionals to discuss patient issues. Therefore, E-Healthcare data management plays a crucial role in modern hospitals. Over

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Internet and cloud services, digitized healthcare systems have provided easy access, viewing and sharing of digitized medical images to patients, doctors, medical professionals, health care providers, and institutes of medicine. Medical images may provide for teleconferences among clinicians, interdisciplinary exchanges between radiologists for consultative purposes, and distant learning of medical personnel. For illegal purposes used for insurance, for example, digital medical malignant nodule images may be modified on lung parenchyma in chest CT scan images. Therefore, data hiding schemes (Wang *et al.*, 2017; Huang *et al.*, 2017; Li *et al.*, 2018; Wang *et al.*, 2018) are much simpler and cheaper than an intrusion detection system (Huang and Hwang, 2012) to protect security and privacy of images by image with a unique digital identity.

Reversible data hiding schemes (Li *et al.*, 2016; Huang *et al.*, 2013a; Chen and Guo, 2020; Kim *et al.*, 2009) (RDH) are applied to embed secrets inside an image as a stego-image with minimal distortion. After the secrets are retrieved from a stego-image at the extraction stage, the original images can be reconstructed exactly. The major applications of RDH are authentication, diagnostic image, military imagery, astronomical images, satellite, and artwork preservation. Shi *et al.* (2016) classified RDH techniques into six categories: histogram shifting, image compressing (e.g., JPEG), semi-fragile authentication, image contrast enhancement, encrypted images, and RDH based on audio and video. In general, there are two types of popular RDH techniques: histogram shifting (HS) (Thodi and Rodriguez, 2007; Hong *et al.*, 2008) and difference expansion (DE). In 2006, Ni *et al.* (2006) proposed the first HS-based RDH by modifying the generated histogram. Some extensions of Ni *et al.*'s HS-based RDH methods proposed such as block-based HS (Falahpour and Sedaaghi, 2007), difference-histogram (Lee *et al.*, 2006), high-frequency IWT coefficients (Xuan *et al.*, 2007; Huang *et al.*, 2017). In 2002, Tian (2002) proposed a high capacity DE method. Furthermore, DE has been developed in three species: integer-to-integer transformation (Qiu *et al.*, 2016), prediction-error expansion (PEE) (Dragoi and Coltuc, 2015), and adaptive embedding (Hong *et al.*, 2015). There are three approaches in image compressing: RDH with quantized DCT coefficients modification (Huang *et al.*, 2016), RDH with quantization table modification (Wang *et al.*, 2013), RDH with Huffman table modification (Wu and Deng, 2011). In 2003, Vleeschouwer *et al.* (2003) presented the first robust RDH based on the correlations among the neighbouring pixels. In general, the approaches of contrast enhancement RDH applied some functionalities such as histogram bin expansion operations to improve the visual quality. There are four RDH approaches with contrast enhancement: method by histogram bin expansion (Wu *et al.*, 2015a), method with contrast enhancement for medical images (Wu *et al.*, 2015b), method with the controlled contrast enhancement (Gao and Shi, 2015), and automatic contrast enhancement method (Kim *et al.*, 2015). Due to protection of the privacy of data and enabling the cloud server to easily manage the data, more and more researchers study reversible data hiding in encrypted images. The techniques of encrypted images are divided into three types: vacating room before encryption (Cao *et al.*, 2016), vacating room after encryption (Zhang, 2011), and reversible image transformation (Zhang *et al.*, 2016).

Considering resource sharing data in Cloud computing environments, stego-images may be disturbed by various techniques such as a chaotic Hénon function to obtain en-



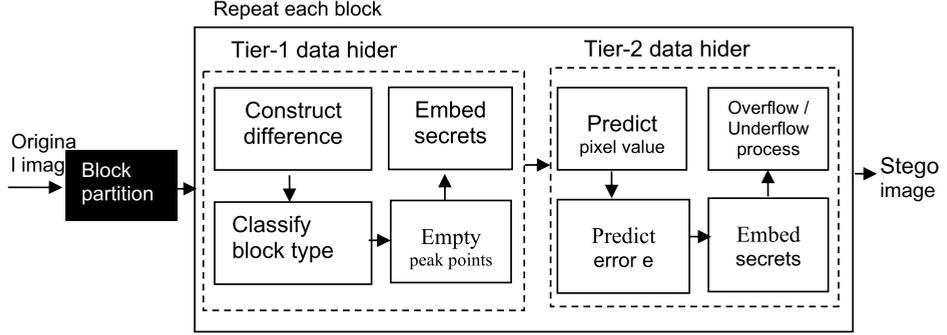


Fig. 2. Diagram for the framework of two-tier medical image data hiding based on histogram shifting of prediction errors at the sender side.

sists of four steps: constructing difference, classifying block type, emptying peak points, and embedding data.

### Step 1: Construct difference

At this step, we find median values of each block. Let four pixel values  $v_j$ , where  $1 \leq j \leq 4$ , be retrieved from each difference block. Then these pixel values are sorted in an ascending order  $s_1 \leq s_2 \leq s_3 \leq s_4$ . The median of  $v_m$  is defined as

$$v_m = s_{\lfloor \frac{p \times q}{2} \rfloor}, \quad \text{where } p = 2 \text{ and } q = 2.$$

In order to construct a difference histogram in the block, we will compute the difference between  $v_m$  and the other  $(p \times q) - 1$  pixels as follows:

$$d_k = v_k - v_m, \quad \text{where } 1 \leq k \leq p \times q, k \neq m. \quad (1)$$

### Step 2: Classify block type

In this step, all blocks will be classified into two types, Type I and Type II. Let  $n_L$ ,  $n_0$  and  $n_R$  be the numbers of pixel values, which are smaller, equal and larger than  $v_m$  in a block, respectively. Therefore, we will obtain  $n_L + n_R + n_0 = p \times q$  where  $p$  and  $q$  are equal to 2. So each block will be labelled with the type number for embedding at this stage. In other words, different kinds of block types will be processed by different embedding procedure.

### Step 3: Empty peak points

Embedding level (EL) is a parameter to adjusting capacity by histogram shifting. Let  $EL = i$ , the bins of  $b_{\pm(i+1)}$ ,  $b_{\pm(i+2)}$ ,  $b_{\pm(i+3)}$ ,  $\dots$ ,  $b_{\pm(2i+1)}$  will be emptied by shifting the bins  $[b_{-(i+1)}, b_{-(2^{bit\_depth}-1)}]$  leftward and  $[b_{+(i+1)}, b_{+(2^{bit\_depth}-1)}]$  rightward where the histogram bins are denoted by  $b_{-(2^{bit\_depth}-1)}, \dots, b_0, \dots, b_{+(2^{bit\_depth}-1)}$ . For instance,  $i = 2$  and bit-depth = 8 will empty the bins  $b_{\pm 3}$ ,  $b_{\pm 4}$ ,  $b_{\pm 5}$  by shifting the bins  $b_{-3 \leq i \leq -127}$  leftward and the bins  $b_{3 \leq i \leq 128}$  rightward. These operations are described by the formula

as follows:

$$d'_k = \begin{cases} d_k + EL + 1 & \text{if } d_k > EL, \\ d_k - EL - 1 & \text{if } d_k < -EL, \\ d_k & \text{otherwise,} \end{cases} \quad (2)$$

where  $1 \leq k \leq p \times q, k \neq m$ .

$$s'_k(i, j) = \begin{cases} s_k(i, j) + EL + 1 & \text{if } d_k(i, j) > EL, \\ s_k(i, j) - EL - 1 & \text{if } d_k(i, j) < -EL, \\ s_k(i, j) & \text{otherwise,} \end{cases} \quad (3)$$

where  $1 \leq k \leq p \times q, k \neq m$ .

**Step 4: Embed data**

In this step, we apply histogram shifting to differentiate types of blocks. The strategies of the secret embedding are demonstrated as follows:

**(1) Type I.**

The definition of Type I is

$$n_L = \left\lfloor \frac{p \times q}{2} \right\rfloor - 1, \quad n_0 = 1, \quad n_R = \left\lfloor \frac{p \times q}{2} \right\rfloor. \quad (4)$$

The secrets will be embedded as Eq. (4) repeatedly.

$$d''_k = \begin{cases} d'_k + EL + w & \text{if } d'_k = EL, \\ d'_k - EL - w & \text{if } d'_k = -EL, \end{cases} \quad (5)$$

where  $1 \leq k \leq p \times q, k \neq m$ .

**(2) Type II-1.**

The definition of block Type II-1 is presented as follows:

$$\begin{cases} n_0 \geq 2, \\ 0 \leq n_R = n_L \leq \left\lfloor \frac{(p \times q) - n_0}{2} \right\rfloor. \end{cases} \quad (6)$$

We will apply Eq. (6) to embed secrets  $w$  repeatedly.

$$d''_k = \begin{cases} d'_k + (-1)^{t+1} & \text{if } d'_k = v_m \text{ and } w = 1, \\ d'_k & \text{if } d'_k = v_m \text{ and } w = 0, \end{cases} \quad (7)$$

where  $1 \leq k \leq p \times q, k \neq m$ .  $t$  is the number of  $n_0$  and  $t \geq 2$ . In other words, the first one will not be applied to the formula (6) to embed a bit.

**(3) Type II-2.**

In a Type II-2 block, the definition is demonstrated as

$$\begin{cases} n_0 \geq 2, \\ 0 \leq n_L < n_R \leq (p \times q) - n_0, \end{cases} \quad (8)$$

$$d_k'' = \begin{cases} d_k' - 1 & \text{if } d_k' = 0, w = 1, t < n_R - n_L, \\ d_k' + (-1)^{t+1} & \text{if } d_k' = 0, w = 1, t \geq n_R - n_L, \\ d_k' & \text{if } d_k' = 0, w = 0, \end{cases} \quad (9)$$

where  $1 \leq k \leq p \times q, k \neq m$ .  $t$  is the number of  $n_0$ .

**(4) Type II-3.**

In a Type II-3 block, the definition is demonstrated as

$$\begin{cases} n_0 \geq 2, \\ 0 \leq n_R < n_L \leq (p \times q) - n_0, \end{cases} \quad (10)$$

$$d_k'' = \begin{cases} d_k' + 1 & \text{if } d_k' = 0, w = 1, t \leq n_L - n_R, \\ d_k' - (-1)^{t+1} & \text{if } d_k' = 0, w = 1, t > n_L - n_R, \\ d_k' & \text{if } d_k' = 0, w = 0, \end{cases} \quad (11)$$

where  $1 \leq k \leq p \times q, k \neq m$ .  $t$  is the number of  $n_0$ .

**2.1.2. Tier-2 Data Hiding**

In order to adjust the quality of stego-image, we apply threshold in the embedding process. Let a set of  $2 \times 2$  sized block have four elements ( $a, b, c, d$ ) shown in Fig. 1. Assume the difference value (DV) is  $\sum_{i=1}^3 |\text{element}_i - \text{element}_4|$ . When  $DV \leq \text{threshold}$ , the Tier-2 data hiding will be performed. The details of Tier-2 data hiding are described as follows.

**Step 1:** Compute the prediction pixel value

$$\hat{p} = \begin{cases} \min(c, d), & \text{if } b \geq \max(c, d), \\ \max(c, d), & \text{if } b \leq \min(c, d), \\ c + d - b, & \text{otherwise.} \end{cases} \quad (12)$$

**Step 2:** Compute the prediction error  $e$

Let predict pixel  $p$  be an element  $a$

$$e = p - \hat{p}. \quad (13)$$

**Step 3:** Data embedding

$$\tilde{p} = \hat{p} + 2 \times e + w, \quad (14)$$

where  $w$  is the secret bit.

**Step 4:** Overflow/Underflow process

In order to restore the cover image correctly, we process the overflow/underflow by the shifting histogram from the embedding stage without a location map or compression (Kim *et al.*, 2009). At first, we compute the utilization rate of the medical image which consists of intensity rate and underflow/overflow rate. In order to get the intensity rate, we divide the range of intensity by 2 to the power of bit depth. The range of intensity is the difference in the intensity of the cover image between max value and min value. Bit depth is the image quality expressing how many unique shades are available. Images with higher bit depths are able to encode more intensities because there are combinations of 0's and 1's available.

$$\text{Intensity rate} = \frac{\text{The range of intensity}}{2^{\text{bit\_depth}}}, \quad (15)$$

$$\text{Underflow/Overflow rate} = \frac{\text{Value of under flow/overflow}}{2^{\text{bit\_depth}}}, \quad (16)$$

$$\text{The utilization rate} = |\text{intensity rate}| + |\text{underflow/overflow rate}|. \quad (17)$$

Further, we adjust image histograms to prevent overflow/underflow problems. On low underflow/overflow rates of high bit-depth medical images, unsigned bit images will produce underflow problems.

Because modern medical devices provide high quality images, medical images can range from 0 to 65535 for a 16-bit image. Therefore, the utilization rate of 16-bit depth is lower than 8-bit depth shown in equations (15), (16). In other words, we can utilize empty histogram bin to process overflow/underflow problem by shifting histogram of the whole image.

In respect of preserving boundary pixels, our method can restore the original-image from the stego-image successfully. Thus, the boundary pixels will be preserved. After the process of embedding, our method also can preserve the boundary pixels shown in Fig. 5. The 16-bit depth unsigned images are tested with threshold 21. In Fig. 5(b) and (c) the preserved boundary of the medical image when EL are changed from 5 to 20 is shown. In the same way, another test of the preserved boundary is shown in Fig. 5(e), (f).

## 2.2. Data Extraction

In order to extract data, we need the embedding level and overflow/underflow distance as parameters. The data extraction will extract secret messages correctly and restore the stego-image back to the original without any distortions, described in detail below as shown in Fig. 3. Similar to the data embedding process, we partition the stego-image into overlapping blocks with  $2 \times 2$  block-size at the first step. The extraction process comes in the reverse direction of the embedding. Thus, the start block of the extraction comes from the right side of the bottom image. At the same time, the extrication direction follows the principle of right-to-left and bottom-to-top. After the block partition, each block will perform two tier data extraction to obtain secrets repeatedly. The detail is described as follows.

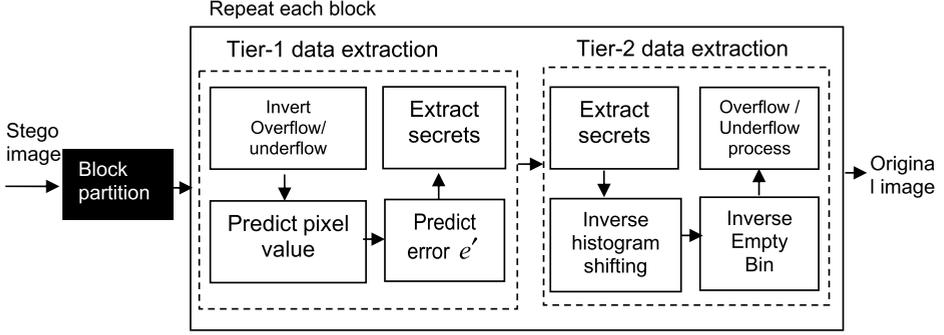


Fig. 3. Diagram for the framework of two-tier medical image data extraction based on histogram shifting of prediction errors at receiver side.

### 2.2.1. Tier-2 Data Extraction

In tier-2 data extraction, we perform the extraction of prediction-based reversible data hiding method. There are four stages: inverting overflow/underflow process, predicting pixel value, predicting error  $e$ , and extracting secrets. At the first stage, we adopt histogram shifting with distance overflow/underflow to invert overflow/underflow process. At the predict pixel value stage, we construct a difference block like in the Tier-1 data hiding, step 2. Then we apply the formula (11) to obtain the predicted pixel value  $\hat{p}$ . And we get the extracted pixel  $\tilde{p}$  at the left-top element of a  $2 \times 2$  block. Then the formula (12) is adopted to obtain predicted error  $e'$  in predicted error  $e'$  stage. The stage of extracting secrets applies  $e'$  to compute the original pixel by  $p = \hat{p} + \lfloor \frac{e'}{2} \rfloor$ . And the secret bit is extracted by  $w = \tilde{p} - \hat{p} - (2 \times (p - \tilde{p}))$ . After extracting secrets, we restore the intermediate image block  $d'''$  for tier-2 data extraction.

### 2.2.2. Tier-1 Data Extraction

There are three stages: extracting secrets, inverting histogram shifting, and inverting empty bin in tier-2 data extraction demonstrated as follows.

#### a. Extracting secrets

In order to extract secrets and restore the original image, we apply histogram shifting to the intermediate image block from tier-1 data extraction at this stage. Let the elements of the intermediate block be  $d_k'''$ , where  $1 \leq k \leq p \times q, k \neq m$ . Set  $EL = 0$  and scan all elements  $d_k'''$ . If  $d_k'''$  is equal to 1 or  $-1$ , a secret bit 1 will be extracted. If  $d_k'''$  is equal to 0, a secret bit is 0.

$$w = \begin{cases} 1 & \text{if } d_k''' \in \{-1, 1\}, \\ 0 & \text{if } d_k''' = 0. \end{cases} \quad (18)$$

Next step, repeat  $n$  times when  $EL$  is equal to  $n$ . In the case  $EL = 1$ ,  $d_k'''$  is  $\pm 3$  and will extract secret bit "1". And  $d_k'''$  is  $\pm 2$  and will extract secret bit "0". In the case  $EL = 2$ ,  $d_k'''$  is  $\pm 5$  and will extract secret bit "1". And  $d_k'''$  is  $\pm 4$  and will extract secret bit "0".

**b. Inversing histogram shifting**

According to Embedding level (EL), there are different strategies to inverse histogram described as follows.

If  $EL = 0$ ,

$$d'_k = \begin{cases} d''_k + 1 & \text{if } d''_k = -1, \\ d''_k - 1 & \text{if } d''_k = 1, \\ d''_k & \text{if } d''_k = 0. \end{cases} \quad (19)$$

If  $EL > 0$ ,

$$d'_k = \begin{cases} d''_k - EL & \text{if } d''_k = 2EL, \\ d''_k - EL - 1 & \text{if } d''_k = 2EL + 1, \\ d''_k + EL & \text{if } d''_k = -2EL, \\ d''_k + EL + 1 & \text{if } d''_k = -2EL + 1. \end{cases} \quad (20)$$

**c. Inversing empty bin**

If EL is greater than 0, we perform the inversion of empty bin according to the following formula:

$$d_k = \begin{cases} d'_k - EL & \text{if } d'_k > EL, \\ d'_k + EL & \text{if } d'_k < EL, \\ d'_k & \text{otherwise,} \end{cases} \quad \text{where } 1 \leq k \leq p \times q, k \neq m. \quad (21)$$

After inversing empty bin, we add a median value of a block to elements of the block. Finally, we construct each block as the original image.

**3. Experimental Results**

In this paper, we demonstrate two-tier medical images data hiding based on histogram shifting of prediction errors to experiment on medical images with DICOM. The peak signal-to-noise ratio (PSNR) is applied to measure the quality.

$$PSNR = 10 \times \log_{10} \frac{255^2}{MSE} \quad (\text{dB}), \quad (22)$$

$$MSE = \frac{1}{W \times H} \sum_{i=1}^w \sum_{j=1}^H (I(i, j) - I'(i, j))^2, \quad (23)$$

where  $W$  and  $H$  are the width and the height of the test image.  $I(i, j)$  and  $I'(i, j)$  are two pixel values of the cover image and stego-image at the location  $(i, j)$ . We test on 16-bit depth CT medical image shown in Fig. 4. In Table 1, we set the embedding level to 1. Different kinds of threshold result in capacity and PSNR. Obviously, the more threshold  $T$ , the more capacity. The more threshold, the smaller PSNR. On the contrary, we set

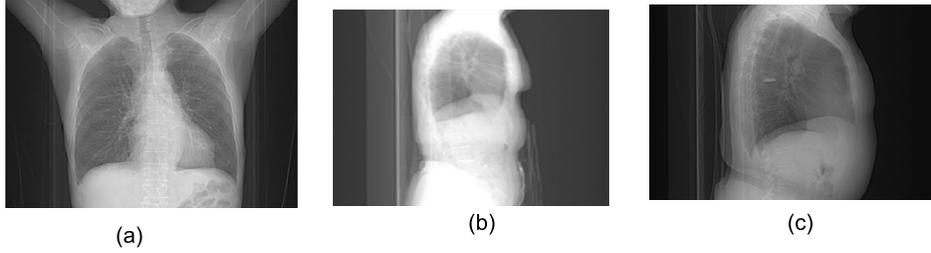


Fig. 4. (a) CT image with signed  $429 \times 512$  (b) CT image with signed  $547 \times 512$  (c) CT image with signed  $350 \times 512$ .

Table 1  
The results for a signed 16-bit grayscale medical image.

Image name from the national cancer imaging archive	Image size	Embedding level	Threshold	Capacity	bpp	PSNR
1.3.6.1.4.1.9328.50.14.2.dcm	$350 \times 512$	1	1	99,633	0.555987723	81.92740097
			6	120,508	0.672477679	79.74795677
			11	150,878	0.841953125	77.48244098
			16	179,047	0.999146205	75.77926976
			21	197,696	1.103214286	74.64371168

Table 2  
The results for an unsigned 16-bit grayscale medical image with different embedding levels.

Image name from the national cancer imaging archive	Image size	Embedding level	Threshold	Capacity	bpp	PSNR
1.3.6.1.4.1.9328.50.14.2.dcm	$350 \times 512$	1	21	197,696	1.103214286	74.64371168
		6		304,972	1.701852679	68.91926164
		11		365,123	2.037516741	66.1103813
		16		406,108	2.266227679	64.16268337
		21		434,770	2.426171875	62.72562295

the threshold to 21 and various embedding levels in Table 2. The greater the embedding level  $E$ , the more capacity, and the smaller PSNR. In Table 3, we set an embedding level and threshold to 21. The largest of bpp is 2.641178445 and the PSNR is 63.24405029.

In this paper, we also used Lena and airplane with 8-bit depth  $512 \times 512$  image shown in Fig. 6. Let the threshold be 1 and the embedding level be 1–4. When bpp is 1.299938202 in the Lena image, the PSNR will be 26.39720695. Because of overflow/underflow processing, the stego-image of Lena will be shifted and the pixels will have poor PSNR. Owing to histogram shifting of the whole image, the most of the image shape will be preserved as shown in Fig. 5 and Table 4. In Fig. 7, we compare a 16-bit grayscale medical image and 8 bit images. We compare the method of median and prediction shown in Table 5. Our method has more capacity at the same PSNR.

Table 3  
The results for a signed 16-bit grayscale medical image.

Image name from the national cancer imaging archive	Image size	Embedding level	Threshold	Capacity	bpp	PSNR
1.3.6.1.4.1.9328.50.14.159.dcm	395 × 512	21	21	501,905	2.481729628	62.81406295
1.3.6.1.4.1.9328.50.14.1207.dcm	429 × 512			574,925	2.617483428	63.33996413
1.3.6.1.4.1.9328.50.14.1210.dcm	429 × 512			515,352	2.346263112	62.08233045
1.3.6.1.4.1.9328.50.14.1278.dcm	444 × 512			526,871	2.317668743	62.05008477
1.3.6.1.4.1.9328.50.14.1280.dcm	444 × 512			589,797	2.594475823	63.22757547
1.3.6.1.4.1.9328.50.14.157.dcm	395 × 512			455,072	2.250158228	61.92850025
1.3.6.1.4.1.9328.50.14.1141.dcm	458 × 512			555,916	2.370684361	62.12956713
1.3.6.1.4.1.9328.50.14.1908.dcm	547 × 512			739,699	2.641178445	63.24405029

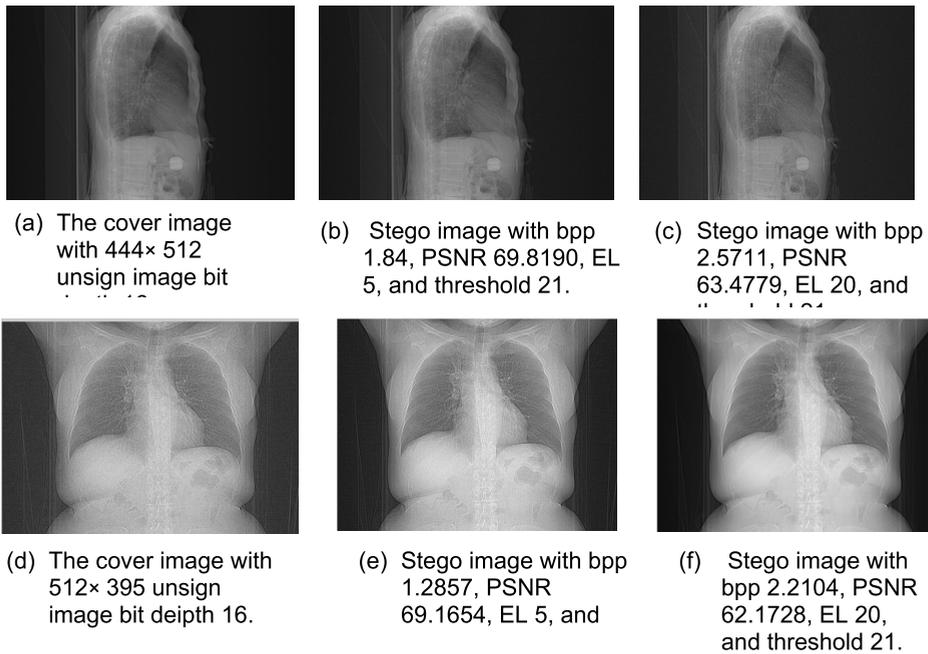


Fig. 5. The result for boundary preserving with EL 5 and 20.

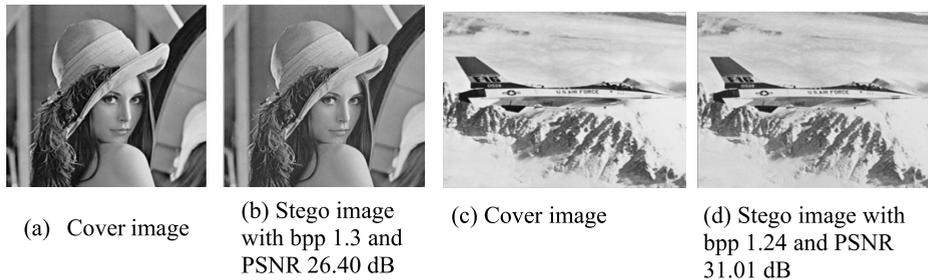


Fig. 6. Two cover images with stego-images: (a), (b) Lena (c), (d) F-16.

Table 4  
The results for Lena and airplane with 8-bit depth.

Image name from the national cancer imaging archive	Image size	Embedding level	Threshold	Capacity bpb	PSNR	
Lena	512 × 512	1	1	158,702	0.605400085	33.63540908
		2		230,835	0.880565643	30.32126065
		3		290,965	1.109943390	28.06630698
		4		340,771	1.299938202	26.39720695
Airplane	512 × 512	1	1	241,027	0.919445038	34.05170498
		2		324,556	1.238082886	31.01245276

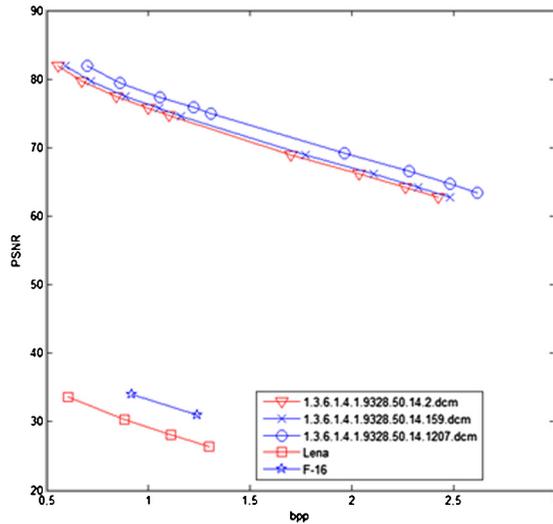


Fig. 7. The results for a 16-bit grayscale medical Image and a 8-bit image.

Table 5  
The results for the comparison of median and prediction methods.

Image name from the national cancer imaging archive	Image size	Median		Prediction		Our method	
		Capacity	PSNR	Capacity	PSNR	Capacity	PSNR
1.3.6.1.4.1.9328.50.14.159	395 × 512	0.71	69.9889	0.99	69.1440	1.68	69.6712
1.3.6.1.4.1.9328.50.14.1207	429 × 512	0.71	69.6336	0.99	69.2379	1.88	69.9551
1.3.6.1.4.1.9328.50.14.1280	444 × 512	0.71	69	0.98	69.747	1.84	69.8189
1.3.6.1.4.1.9328.50.14.1210	429 × 512	0.72	73.6699	0.96	73.396	1.02	73.3560
1.3.6.1.4.1.9328.50.14.1278	444 × 512	0.73	73.3000	0.952	73.063	1.01	73.1843
1.3.6.1.4.1.9328.50.14.157	395 × 512	0.73	73.3590	0.96	73.077	0.96	73.073
1.3.6.1.4.1.9328.50.14.1141	458 × 512	0.73	73.7324	0.96	73.727	1.04	73.459

#### 4. Security Aspects

The embedding algorithm is used to embed the secret data into the cover image as a stego-image. Stego-images are transmitted over the Internet. If stego-images are altered or de-

stroyed due to certain attacks, our method has the basic characteristics of data hiding to protect secret data. Because the secret data is hidden in the cover image, it is difficult for the human visual system to detect any unperceivable secret data.

In our method, there are two layers of block median retention technology and a predictive reversible hiding method to hide secret data. Therefore, our method is a technique that resists the attack of this technique without parameters such as threshold, EL and overflow/underflow methods. We also applied  $2 \times 2$  overlapping blocks to partition the image. If a hacker changes the secure covert image over the network, the secure covert image cannot be extracted correctly.

## 5. Conclusion

We have proposed the data hiding of two-tier medical images based on histogram shifting of prediction error. The median histogram shifting technique and prediction error schemes as the two-tier hiding have high capacity and PSNR in 16-bit medical images. The overlapping block partitions have also been adopted in this scheme, and it has performed well. At the Tier-1 data hider, the median histogram shifting technique is based on a multi-level histogram shifting mechanism. Due to adopting two types of embedding strategies, the block medians are able to be preserved. Therefore, the stego-image utilizes these block medians to convert the stego image to the original image successfully. At the Tier-2 data hider, the prediction error scheme applies a pre-determined threshold and the absolute difference of the neighbouring pixels to decide whether the current pixel is embeddable.

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In this paper, we adopt medical images from the cancer imaging archive (NBIA, 2018) and thank National Cancer Institute for providing the CT image data for this study for free. Most of the medical devices provide 16 or more bits of image information at each pixel (Culjat *et al.*, 2012). Therefore, a very large number of histogram is empty. Those histograms can be utilized to process overflow/underflow problems.

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